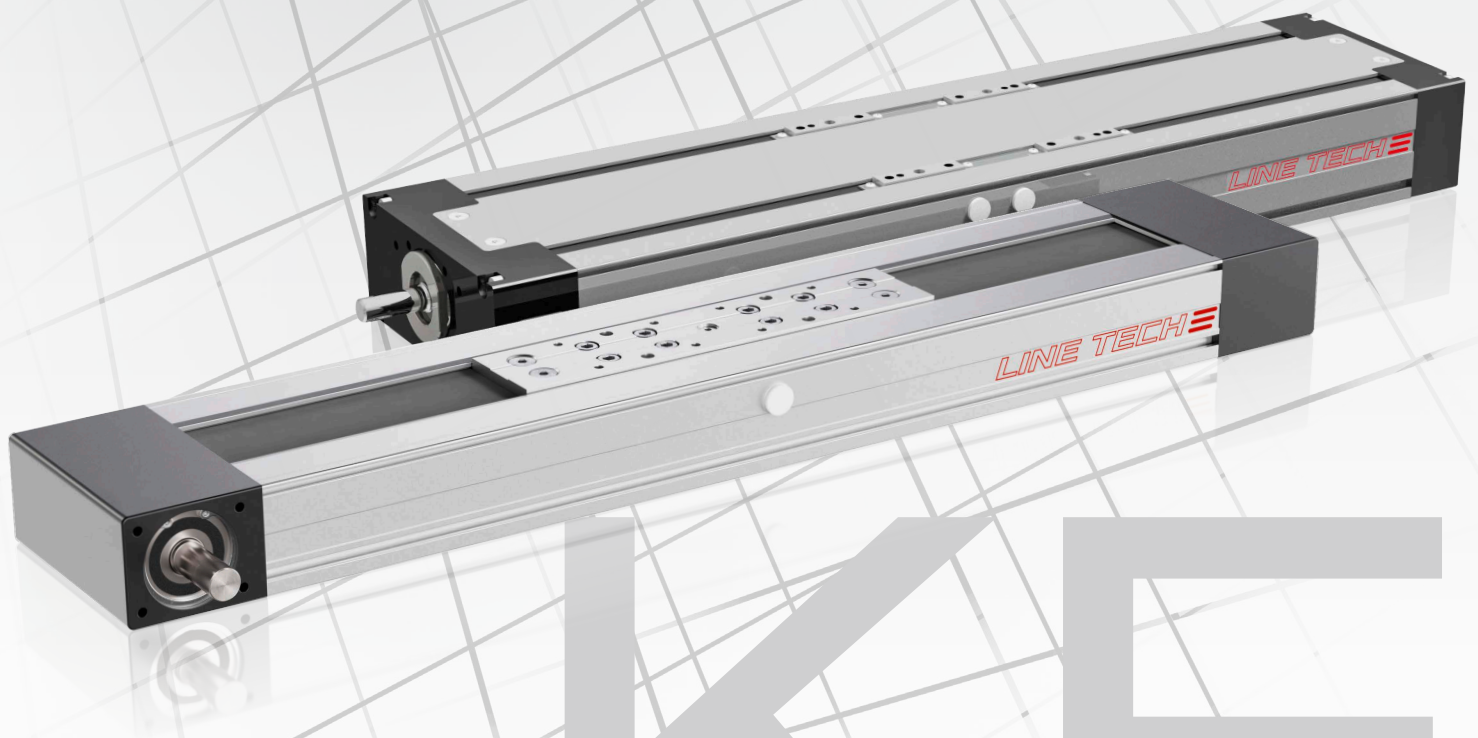


*LINE TECH* 



# KE

**COMPACT UNITS**  
PRODUCT CATALOGUE

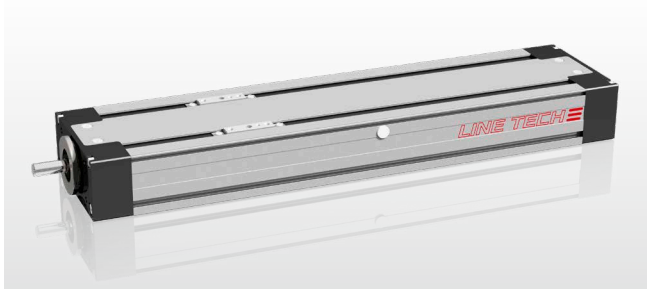
SWISS MADE LINEAR TECHNOLOGY 



## Product overview

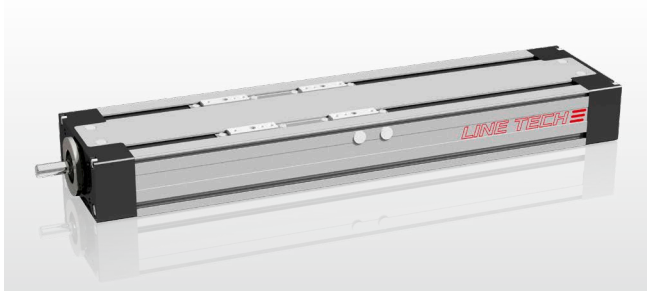
### KE...2...R...

Compact unit with one carriage and ball screw drive



### KE...4...R...

Compact unit with two carriages and ball screw drive



### KE...2...Z...

Compact unit with short carriage (2 runner blocks) and toothed belt drive



### KE...4...Z...

Compact unit with long carriage (4 runner blocks) and toothed belt drive



## Content

### Compact units KE...

- Product overview	<a href="#">3</a>
- Design fundamentals / Lubrication / Maintenance	<a href="#">4</a>
- Profile cross-sections	<a href="#">5-6</a>
- Compact unit with ball screw drive	
- Details for ball screw drive	<a href="#">7</a>
- General technical details for compact units	<a href="#">8</a>
- Load ratings and torques	<a href="#">9</a>
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### Compact units KE...R... with ball screw drive

- Designation system	<a href="#">16-17</a>
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- KE2.2...AR... with 1 carriage and protective ribbons	<a href="#">22</a>
- KE2.4...AR... with 2 carriages and protective ribbons	<a href="#">23</a>
- KE3.2...AR... with 1 carriage and protective ribbons	<a href="#">24</a>
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### Compact units KE...Z... with toothed belt drive

- Designation system	<a href="#">26-27</a>
- Information for selection » Motor mounting	<a href="#">28-30</a>
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- Dimensions	
- KE2.2...Z... with 2 runner blocks (short carriage)	<a href="#">32</a>
- KE2.4...Z... with 4 runner blocks (long carriage)	<a href="#">33</a>

### Compact units KE...

- Limit switches; fitting / preparation / plug	<a href="#">34-35</a>
- Motor mounting straight/lateral with ball screw	<a href="#">36-37</a>
- Motor mounting straight/lateral with toothed belt	<a href="#">38-39</a>
- Connecting plates for KE...R...	<a href="#">40-41</a>
- Connecting plates for KE...Z...	<a href="#">42-43</a>
- Attachment accessories; clamps / T-slot nuts	<a href="#">44-45</a>
- Cross table mounting	<a href="#">46</a>
- Lubrication points at KE...R...	<a href="#">47</a>
- Lubrication points at KE...Z...	<a href="#">48</a>
- Lubrication points for customer add-on	<a href="#">49</a>



## Product overview

LINE TECH compact units are precise, ready-to-install, modular linear systems with linear rail guides and ball screw or toothed belt drive, designed for high performance. Areas of application are linear systems for medium loads and high-precision requirements. Three sizes (KE1, KE2 and KE3 – with ball screw drive) resp. one size (KE2 – with toothed belt drive) are currently available.

### Advantages

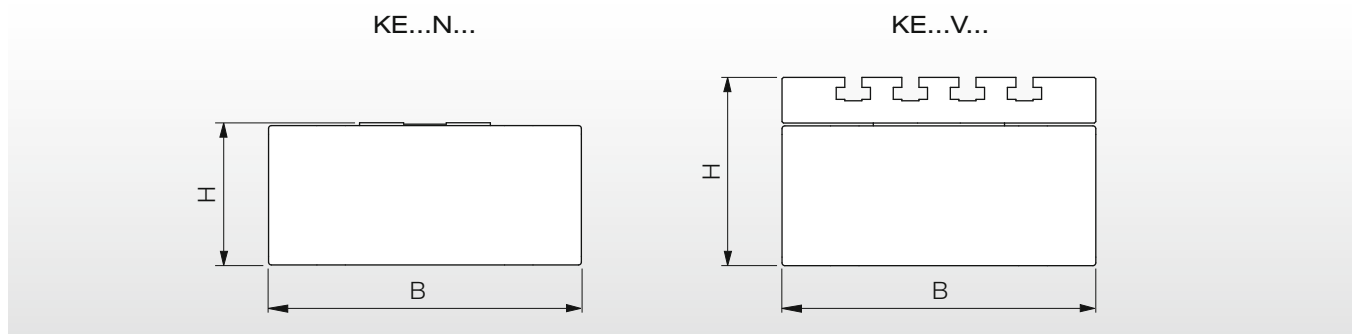
- Compact size
- Optimal movement characteristics in conjunction with high load ratings and high rigidity provided by two (KE...2...) or four (KE...4...) integrated runner blocks
- Drive via ball screw or toothed belt
- Simple motor mounting via centring and mounting thread on the drive housing
- Lubrication via centralised lubrication points
- Customised layout for specific applications possible

### Design

- Compact aluminium profile as base profile
- Ready-to-install compact units in any length
- Aluminium carriage

### Options available on request

- Connecting plates (KE...V...)
- Motor attachments
- Limit switches
- Cross table mounting
- Multi-axis systems



Compact unit Type	Dimensions B x H [mm]	Load ratings	
		C <sub>0</sub> [kN]	C [kN]
KE1.2...N...	90 x 40	11.2	6.5
KE1.2...V...	90 x 56	11.2	6.5
KE1.4...N...	90 x 40	22.5	13.0
KE1.4...V...	90 x 56	22.5	13.0
KE2.2...N...	110 x 50	35.0	18.0
KE2.2...V...	110 x 66	35.0	18.0
KE2.4...N...	110 x 50	70.0	36.0
KE2.4...V...	110 x 66	70.0	36.0
KE3.2...N...	145 x 65	59.9	34.2
KE3.2...V...	145 x 85	59.9	34.2
KE3.4...N...	145 x 65	119.9	68.4
KE3.4...V...	145 x 85	119.9	68.4

See pages [7 to 15](#) for further technical data.

## Design fundamentals / Lubrication / Maintenance

### LINE TECH Compact Units

LINE TECH compact units are modular, ready-to-install linear systems including the drive. Sealed guide elements are used in all sizes.

The guides and drive are protected against external influences such as dirt, debris, etc. by synthetic ribbons resp. by the toothed belt.

The base profile and cover profile are extruded aluminium alloy. Additional externally mounted limit switches in conjunction with motors and a control unit ensure the correct positioning of the carriage and prevent overshoot.

The design delivers very high performance with extremely compact dimensions.

### Lubrication

The guide elements of LINE TECH compact units are pre-lubricated at the factory with Microlube GBU Y 131.

Correct and sufficient lubrication can significantly extend the service life of the compact units. Periodic lubrication should be conducted in accordance loads handled and field of application. In general, lubrication should be carried out every 500 hours.

All roller bearings used are lubricated for life and therefore require no maintenance.

**Note:** See pages [47–49](#) for information on the lubrication points.

### Maintenance

Except for periodic lubrication, LINE TECH compact units are maintenance free.

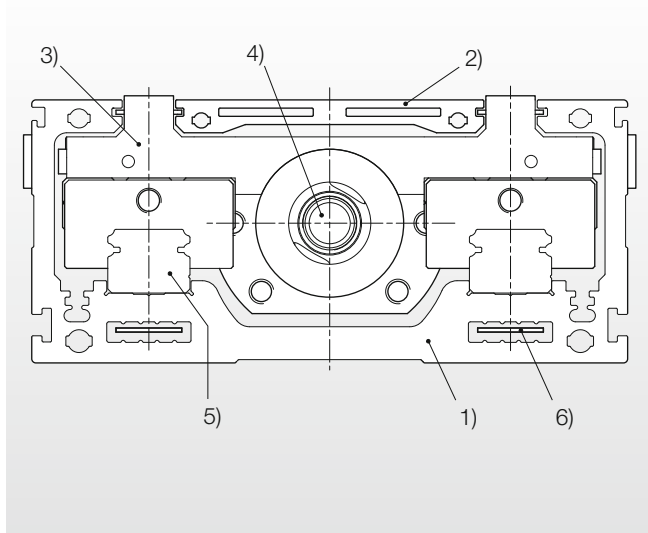
### Operating temperature

The permissible operating temperature of between 5 and 80 °C is determined by the plastic components.

The specifications of the respective manufacturers of motors and controls apply.

### KE...R...

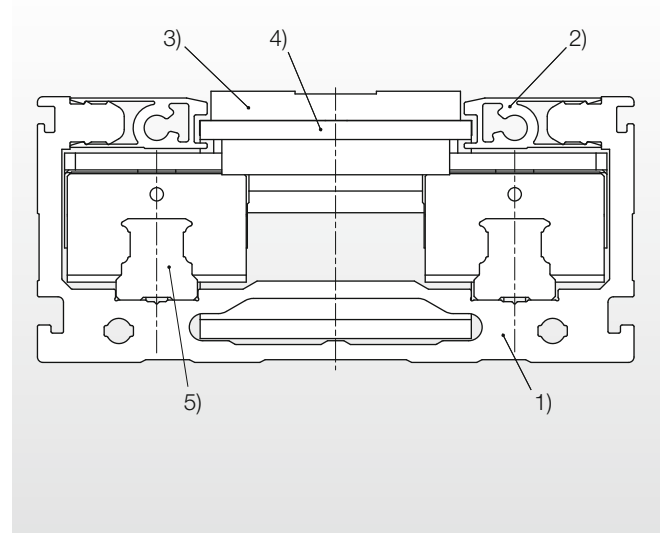
with ball screw drive



- 1) Base profil
- 2) Cover profile
- 3) One (KE...2...R...) or two (KE...4...R...) Carriages
- 4) Ball screw drive
- 5) Linear guide
- 6) Protective ribbons, circumferential

### KE...Z...

with toothed belt drive



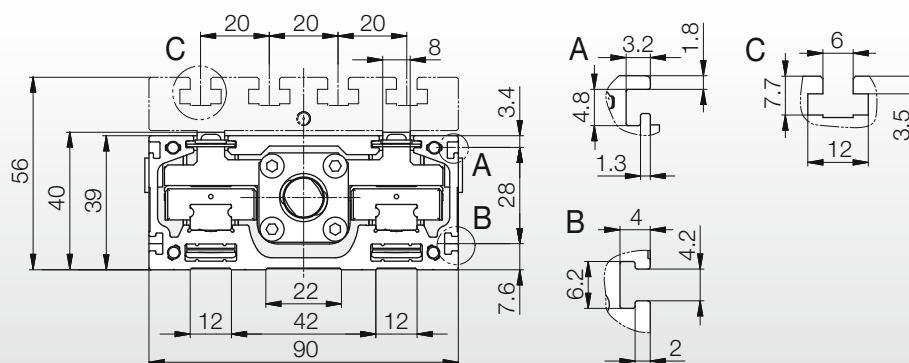
- 1) Base profile
- 2) Cover profile
- 3) Short (KE...4...Z...) or long (KE...4...Z...) Carriage
- 4) Toothed belt
- 5) Linear rail guide

# COMPACT UNITS

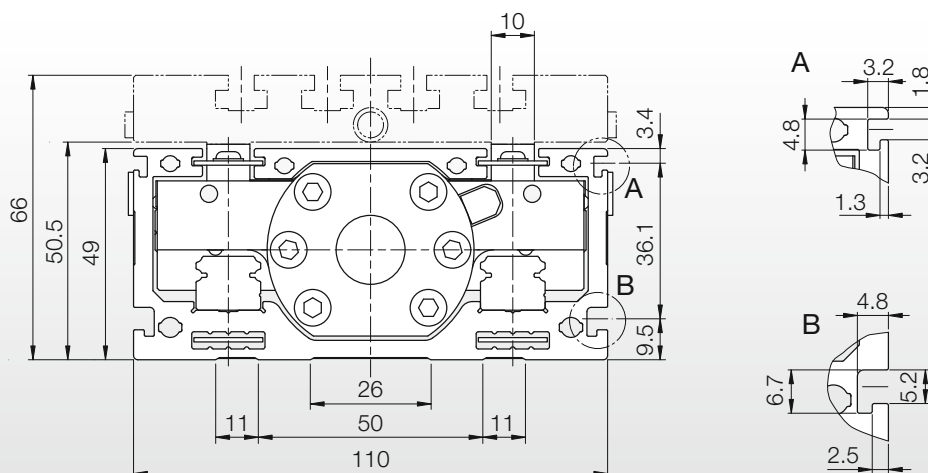


## Profile cross-sections KE...R...

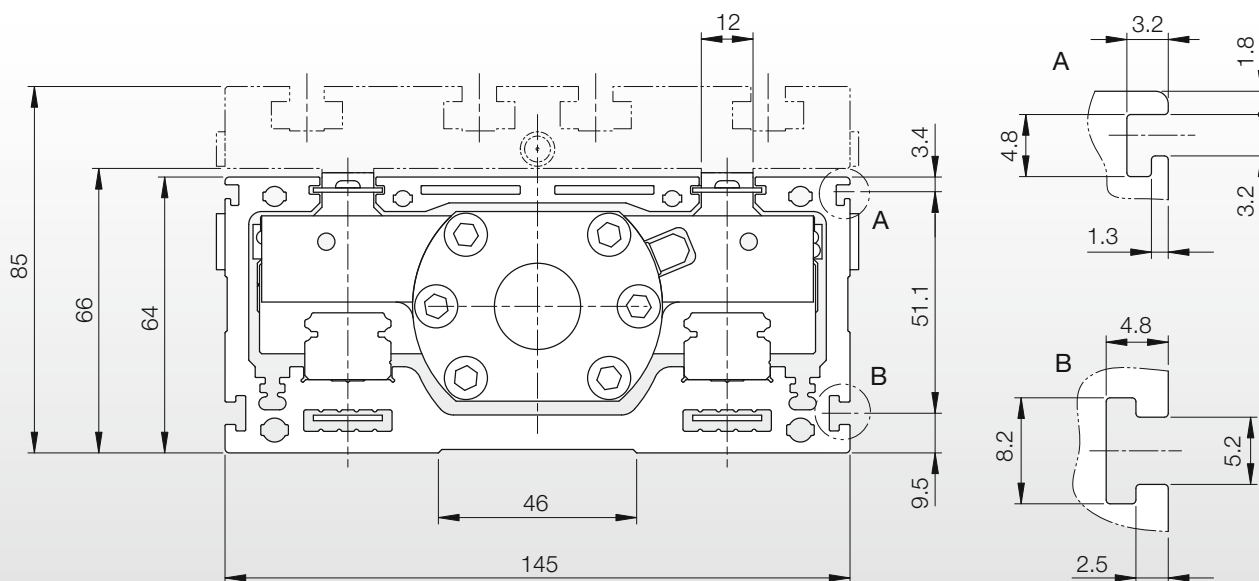
### KE1...R...N



### KE2...R...N



### KE3...R...N

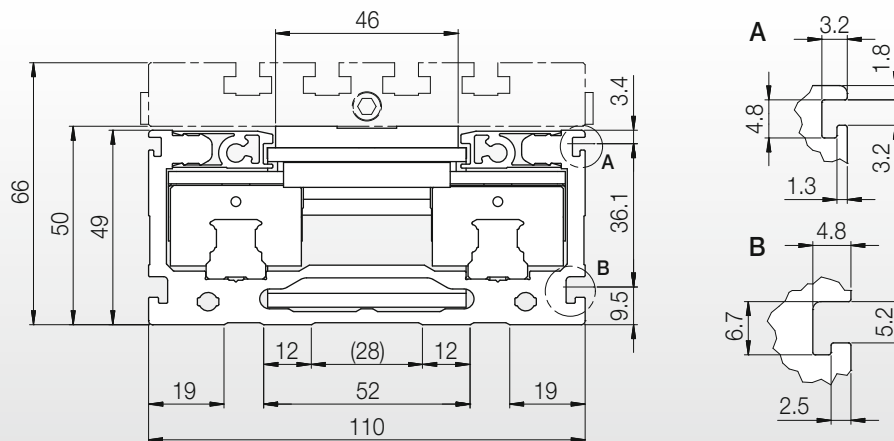


## COMPACT UNIT WITH TOOTHED BELT DRIVE



Cross section KE...Z...

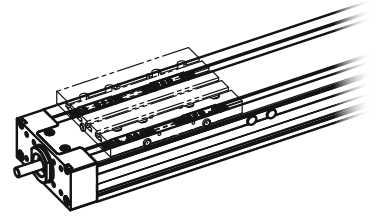
KE2...Z...N



# COMPACT UNITS WITH BALL SCREW DRIVE



## Details for ball screw drive



## Details for ball screw drive (BSD)

KE	BSD	Axial load rates		Positioning accuracy	Repeating accuracy	Acceleration	Axial play		Idle torque
		C <sub>0</sub>	C <sub>dyn</sub>				Type	Axial play	
Size	d x p [mm]	[N]	[N]	[μm/mm]	[mm]	a <sub>max</sub> [m/s <sup>2</sup> ]		[mm]	[Nm]
KE1...R...	12 x 5	3333	3099	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.020
					< 0.01 <sup>1)</sup>		V	—	0.090
	12 x 10	3333	3099	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.045
					< 0.01 <sup>1)</sup>		V	—	0.180
KE2...R...	16 x 5	4551	4327	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.030
					< 0.01 <sup>1)</sup>		V	—	0.100
	16 x 10	4551	4327	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.060
					< 0.01 <sup>1)</sup>		V	—	0.200
	16 x 16	4551	4327	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.120
					< 0.01 <sup>1)</sup>		V	—	0.320
KE3...R...	20 x 5	5705	4912	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.050
					< 0.01 <sup>1)</sup>		V	—	0.120
	20 x 10	5705	4912	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.100
					< 0.01 <sup>1)</sup>		V	—	0.250
	20 x 20	5705	4912	52/300	< 0.03 <sup>1)</sup>	10.0	R	< 0.02	0.200
					< 0.01 <sup>1)</sup>		V	—	0.400

d x p = screw diameter x thread pitch

<sup>1)</sup> backlash not factored in

R = reduced play

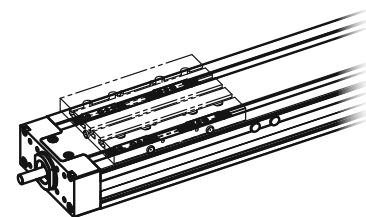
V = preloaded



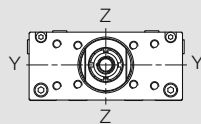
# COMPACT UNITS WITH BALL SCREW DRIVE



## General technical details for compact units



## General technical details for compact units

KE...R...	Movement speed		Moments of inertia		Stroke max.	Protective ribbons	Feed and friction force	Moved mass
	Guide	Drive						
	Type	$v_{\max}$ [m/s]	$v_{\max}$ [m/s]	$I_Y$ [cm <sup>4</sup> ]				
KE1.2...R...	3.0	2)	11.5	95.5	1315	without	8.00	0.370
						with	12.00	
KE1.4...R...	3.0	2)	11.5	95.5	1250	without	12.00	0.680
						with	16.00	
KE2.2...R...	5.0	2)	29.4	242.5	1375	without	10.00	0.790
						with	15.00	
KE2.4...R...	5.0	2)	29.4	242.5	1290	without	15.00	1.370
						with	20.00	
KE3.2...R...	5.0	2)	93.3	746.0	1850	without	15.00	1.460
						with	20.00	
KE3.4...R...	5.0	2)	93.3	746.0	1750	without	20.00	2.470
						with	25.00	

<sup>2)</sup> for ball screw drive, dependent on rotational speed characteristics, spindle length and relevant critical rotational speed.



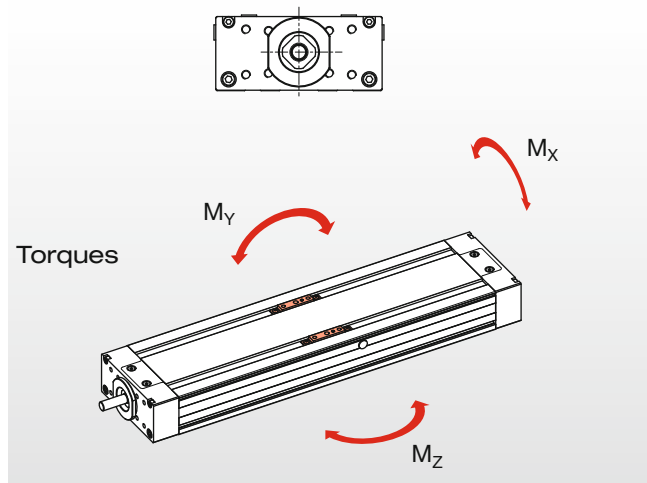


# COMPACT UNITS WITH BALL SCREW DRIVE

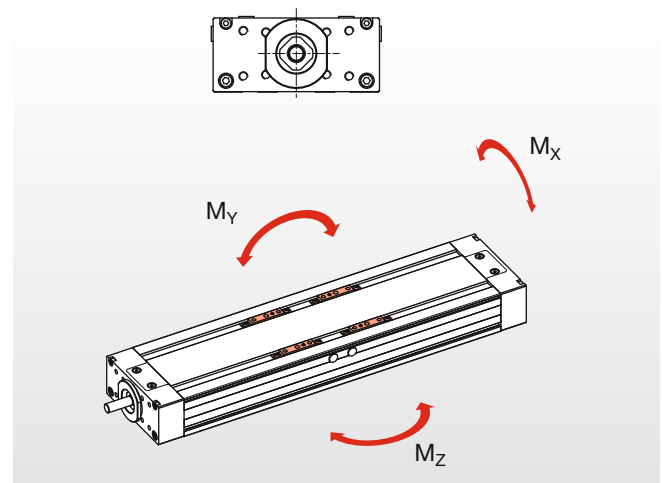


## Load ratings and torques

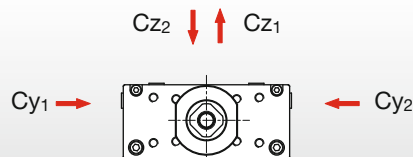
KE...2...R...  
with one carriage



KE...4...R...  
with two carriages



## Load ratings



Compact unit Type	Maximum permissible load [kN]				Maximum permissible torque [Nm]					
	static		dynamic		static			dynamic		
	$C_{y0,1,2}$	$C_{z0,1,2}$	$C_{y1,2}$	$C_{z1,2}$	$M_{x0}$	$M_{y0}$	$M_{z0}$	$M_x$	$M_y$	$M_z$
KE1.2...R...	11.2	11.2	6.5	6.5	275	60	60	158	35	35
KE1.4...R...	22.5	22.5	13.0	13.0	550	330	330	316	210	210
KE2.2...R...	35.0	35.0	18.0	18.0	1064	204	204	590	226	226
KE2.4...R...	70.0	70.0	36.0	36.0	2120	1400	1392	1180	1180	1180
KE3.2...R...	59.9	59.9	34.2	34.2	2427	266	266	1507	202	202
KE3.4...R...	119.9	119.9	68.4	68.4	4854	2100	2100	3014	2044	2044

## Note on dynamic load ratings and torques

The determination of dynamic load ratings and torques is based on a 50,000 m stroke. If comparative values must be calculated for a 100,000 m stroke, the values for  $M_x$ ,  $M_y$ ,  $M_z$  and  $C$  must be divided by the factor 1.26.

## Expedient load

With a view to serviceable life, loads of less than 20% of the dynamic load ratings have generally proved to be expedient.



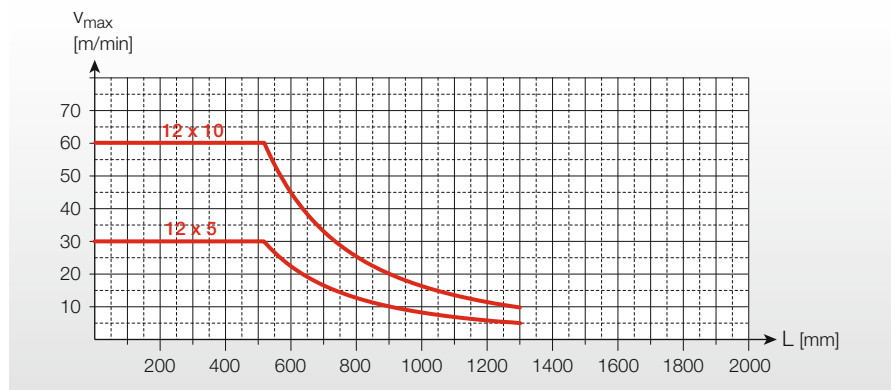
# COMPACT UNITS WITH BALL SCREW DRIVE



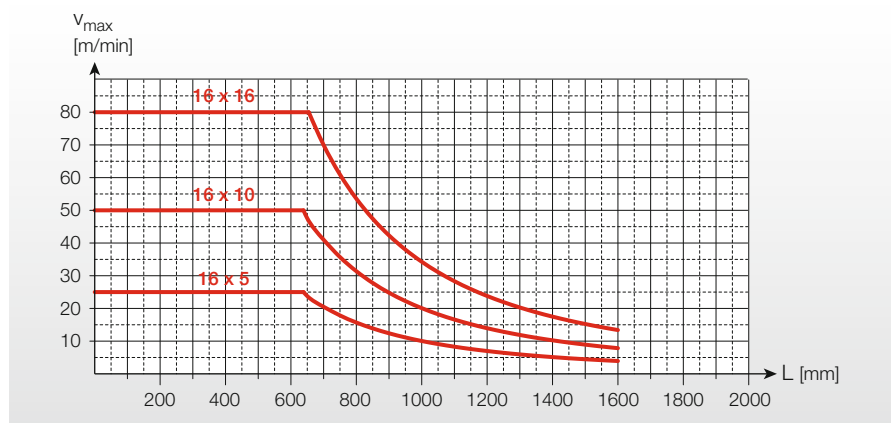
## Permissible speeds

Permissible speeds...

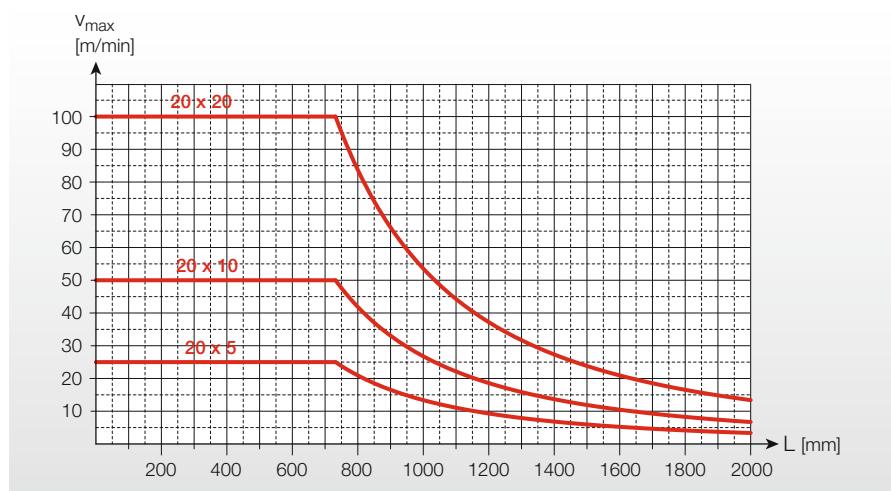
... for KE1...R... with ball screw drive  $\varnothing 12 \times \dots$  <sup>1)</sup>



... for KE2...R... with ball screw drive  $\varnothing 16 \times \dots$  <sup>1)</sup>



... for KE3...R... with ball screw drive  $\varnothing 20 \times \dots$  <sup>1)</sup>



### Attention:

For ball screw drive, note the rotational speed characteristics, spindle length and relevant critical rotational speed.

Please also note the motor speeds!

<sup>1)</sup> higher accuracy on request

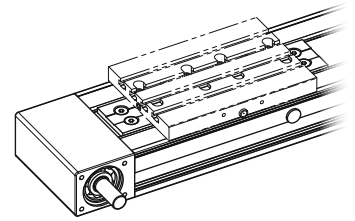
$L$  = overall length of compact unit



# COMPACT UNIT WITH TOOTHED BELT DRIVE



## Data for toothed belt drive



### Technical data for toothed belt drive

KE...Z...	Toothed belt drive				Axial load rating	Positioning accuracy	Repeating accuracy	Accel-eration
Size	Type/Pitch	Toothed pinion $d_3 \times l_R$ [mm]	Stroke/R [mm]	Elongation <sup>2)</sup> [mm/m]	F [N]	[μ/mm]	.../1000 mm [mm]	$a_{max}$ [m/s <sup>2</sup> ]
KE2...Z...	HTD5M	38.2 x 54	120	0.084	<sup>1)</sup>	200/1000 <sup>2)</sup>	< 0.20 <sup>2)</sup>	50.0 <sup>1)</sup>

$d_3 \times l_R$  = Pinion diameter x Pinion width

<sup>1)</sup> Depends on speed and load

→ see "Permissible speeds" chart on page [13](#)

<sup>2)</sup> Belt elongation/metre [mm/m] per 100 N tensile force

### General technical data for compact units with toothed belt drive

KE...Z...	Travel speed		Area moment of inertia		Stroke <sup>4)</sup> max.	Feed and friction force	Mass transported
Type	Guide $v_{max}$ [m/min]	Drive $v_{max}$ [m/min]	$I_Y$ [cm <sup>4</sup> ]	$I_Z$ [cm <sup>4</sup> ]	[mm]	$F_V$ [N]	$m_b$ [kg]
KE2.2...Z...	300	<sup>3)</sup>	32.7	282.9	5700	20	1.29
KE2.4...Z...	300	<sup>3)</sup>	32.7	282.9	5700	40	2.24

<sup>3)</sup> Depends on load, rotation speed, and permissible travel speed of the guides

→ see "Permissible speeds" chart on page [13](#)

<sup>4)</sup> Longer strokes on request



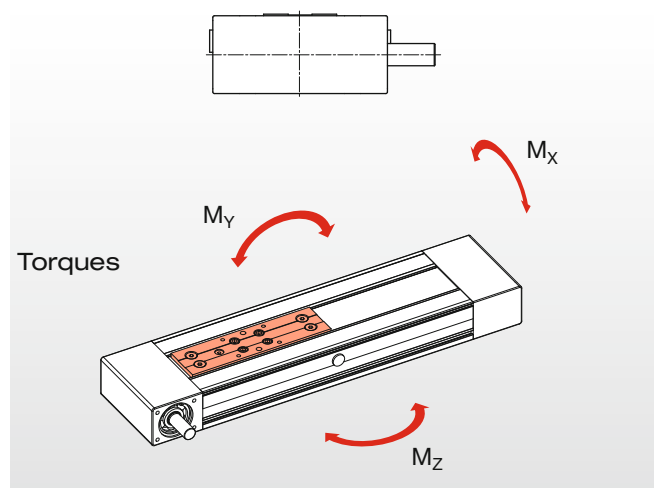
# COMPACT UNIT WITH TOOTHED BELT DRIVE



## Load ratings and torques

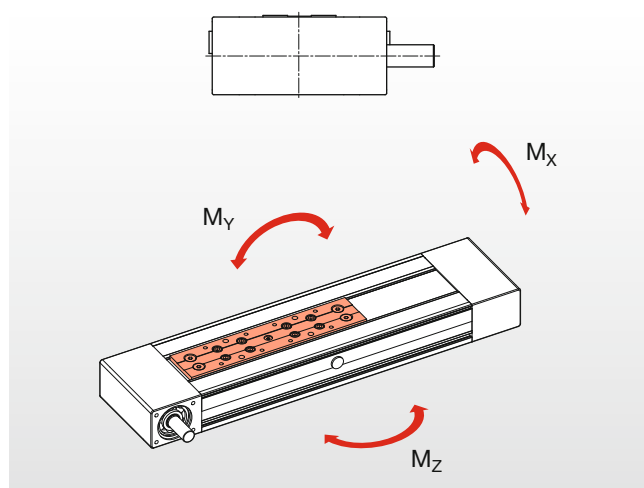
KE2.2...Z...

with short carriage (2 runner blocks)

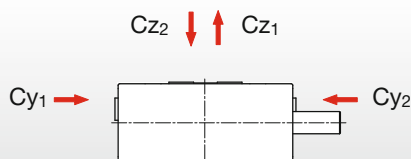


KE2.4...Z...

with long carriage (4 runner blocks)



## Load ratings



Compact unit Type	Maximum permissible forces [kN]				Maximum permissible torques [Nm]					
	static		dynamic		static			dynamic		
	$C_{y0,1,2}$	$C_{z0,1,2}$	$C_{y1,2}$	$C_{z1,2}$	$M_{x0}$	$M_{y0}$	$M_{z0}$	$M_x$	$M_y$	$M_z$
KE2.2...Z...	35	35	18	18	1064	204	204	590	226	226
KE2.4...Z...	70	70	36	36	2120	1926	1820	1180	1542	1542



## COMPACT UNIT WITH TOOTHED BELT DRIVE



### Permissible speed

Permissible speeds...

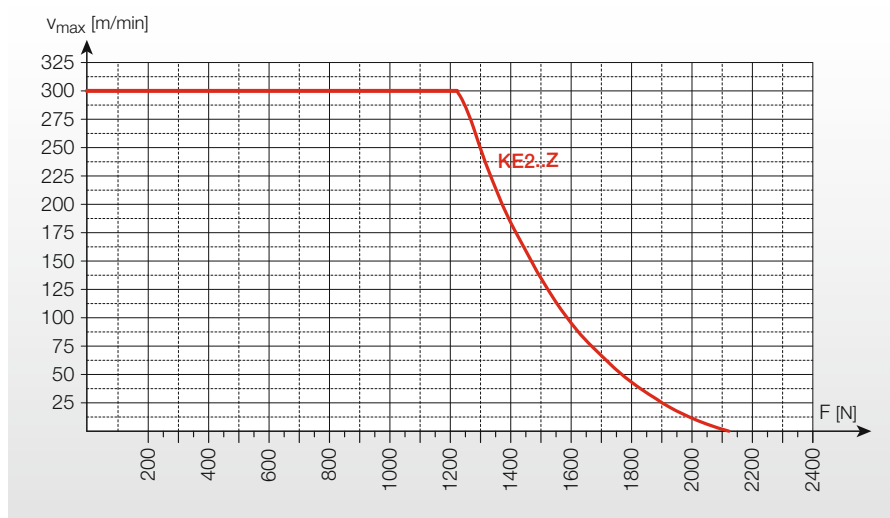
... for KE2...Z... with toothed belt drive

F = axial load

#### Attention:

With toothed belt drive, the permissible travelling speed of the linear rail guides and the load F are critical!

Please also note the motor speeds!



## Permissible deflection (1/2; for KE1... and KE2...)

### Permissible deflection

Compact modules may be mounted self-supporting regardless of the drive type. However, the deflection (which limits the possible load) must be taken into consideration.

If the maximum permissible deflection is exceeded, the compact units must be additionally supported.

The maximum permissible deflection is limited by the maximum deflection angle of 5'. This value being exceeded will have an impact on the unit's life-cycle.

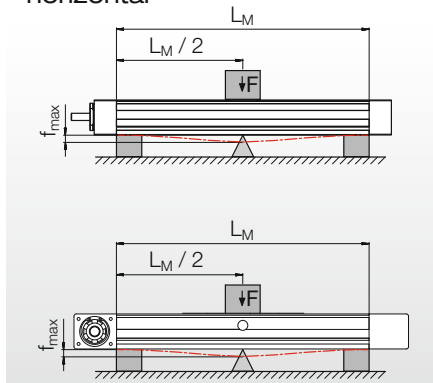
If increased demands are made on system accuracy we recommend supporting the linear modules along its entire length.

The following diagrams apply for:

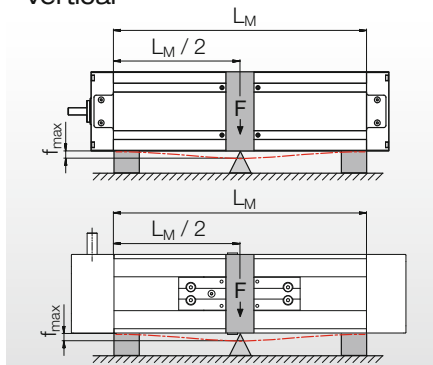
- Firm clamping (40–50 mm per side)
- 3–4 screws per side
- Solid base

### Mounting positions:

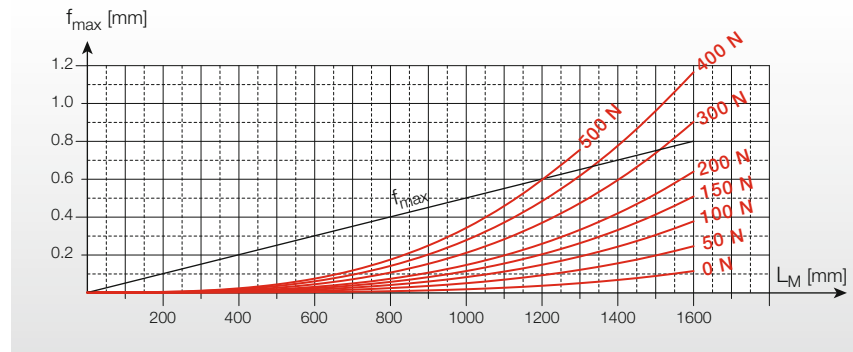
#### - horizontal



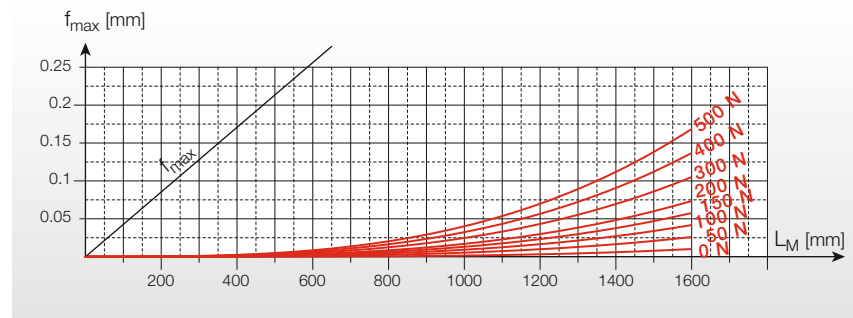
#### - vertical



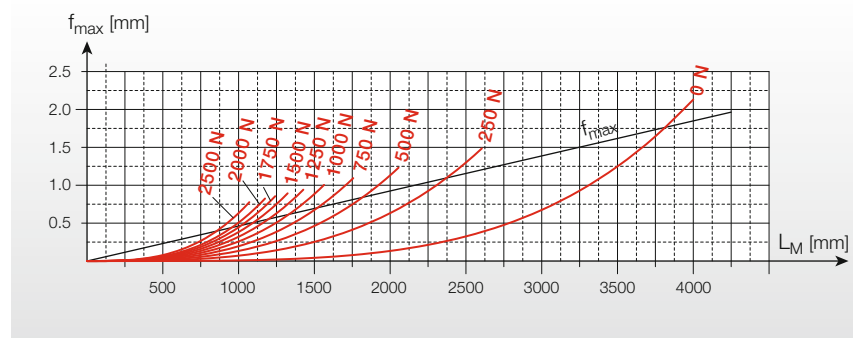
### KE1...R... horizontal



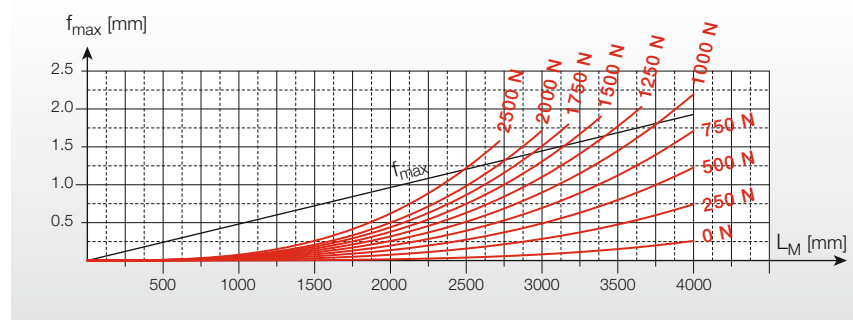
### KE1...R... vertical



### KE2...R/Z... horizontal



### KE2...R/Z... vertical

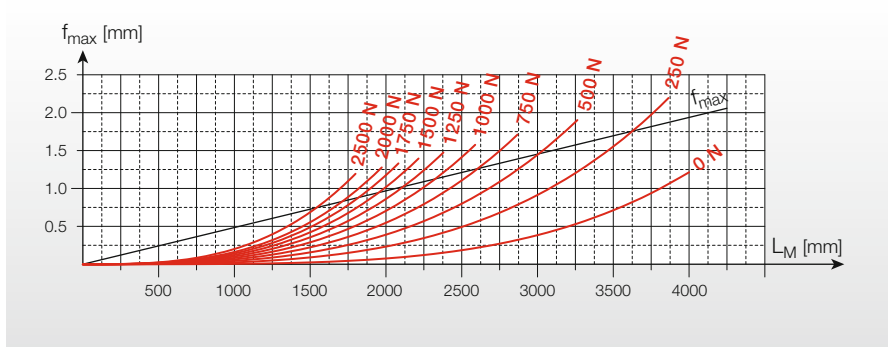


## COMPACT UNITS

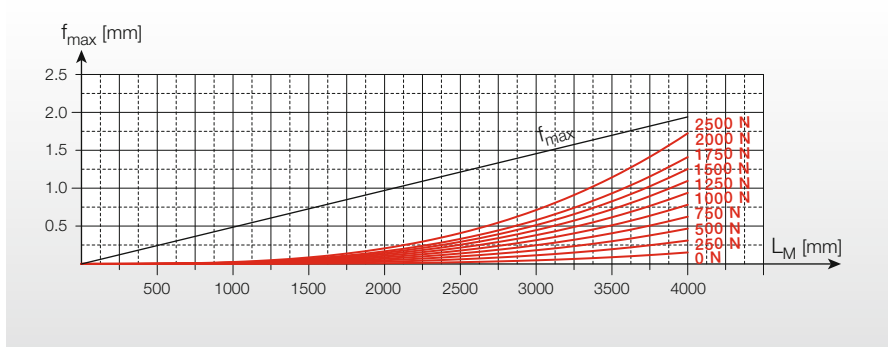


Permissible deflection (2/2; for KE3...)

KE3...R... horizontal

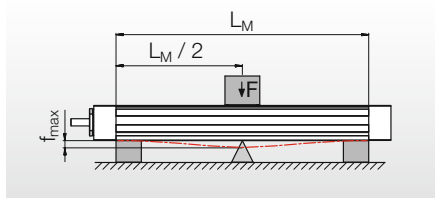


KE3...R... vertical

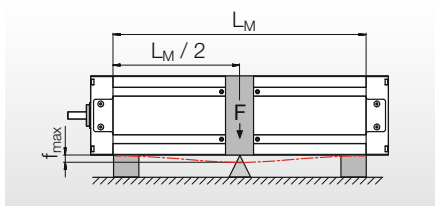


Mounting positions:

– horizontal



– vertical



# COMPACT UNITS WITH BALL SCREW DRIVE



## Designation system

Compact unit (sample designation)

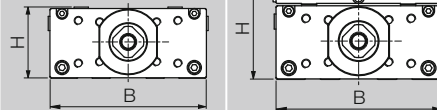
KE 2 . 2 . 0200 A R 005 . 0 .

### Design

KE = compact unit with linear guides

### Size

- 1 = size 90 mm
- 2 = size 110 mm
- 3 = size 145 mm



Size	KE...N... B x H [mm]	KE...V... B x H [mm]
1	90 x 40	90 x 56
2	110 x 50	110 x 66
3	145 x 65	145 x 85

### Configuration

- 2 = 2 runner blocks (1 carriage)
- 4 = 4 runner blocks (2 carriages)

### Stroke absolut [mm]

### Protective covering

- A = synthetic ribbons \*\*\*
- N = without protective ribbons

### Drive

- R = rolled ball screw \*\*\*
- N = without drive

### Stroke per revolution [mm]

- 005 / 010 = size 1; ball screw with a pitch of 5 or 10 mm
- 005 / 010 / 016 = size 2; ball screw with a pitch of 5, 10 or 16 mm
- 005 / 010 / 020 = size 3; ball screw with a pitch of 5, 10 or 20 mm
- ... = other pitch <sup>1)</sup>

### Limit switches

- 0 = without limit switch
- 1 = 2 limit switches, reference point at front (drive side); limit switch designs N and C are possible
- 2 = 2 limit switches, reference point at rear (opposite drive side); limit switch designs N and C are possible
- 3 = 2 limit switches + additional reference switch at front (drive side); only limit switch design N is possible
- 4 = 2 limit switches + additional reference switch at rear (opposite drive side); only limit switch design N is possible

\* seen from motor opposite side towards motor

\*\* available for lateral motor mounting only

\*\*\* standard version

<sup>1)</sup> on request







01 . 0 N - N 7 R N N N

5 8 3 - - - → 583... = Drawing type

#### Buffers

N = with integrated buffers

#### Limit switch design

N = with plain-end cable, L = 2.0 m \*\*\*

C = with connector plug M8 (with max. 2 limit switches; see p. 16)

#### Mounting position of limit switches

N = without limit switches \*\*\*

L = limit switches mounting left \*

R = limit switches mounting right \*

#### Preload ball screw drive (BSD)

V = BSD preloaded \*\*\*

R = BSD with reduced play

N = without drive

#### Tolerance class ball screw (BSD)

7 = Tolerance class BSD: T7 (52 µm/300 mm) \*\*\*

N = without drive

#### Connecting plate (see pages 40/41)

N = without connecting plate \*\*\*

V = with connecting plate

#### Motor mounting

N = without motor mounting \*\*\*

F = mounting plate for standard motor

S = mounting plate for special motor

#### Reduction

0 = without reduction (1:1) \*\*\*

1 = reduction 1:1.5 \*\*

2 = reduction 1:2 \*\*

#### Delivery condition (see page 18)

00 = without drive

01 = free spindle end \*\*\*

02 = with coupling and intermediate plate

03 = with crank and clamp

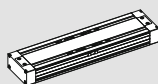
04 = set up for lateral motor mounting right \*

05 = set up for lateral motor mounting left \*

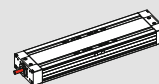
06 = set up for lateral motor mounting top

07 = set up for lateral motor mounting bottom

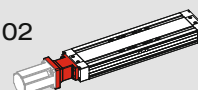
00



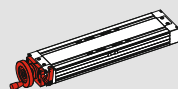
01



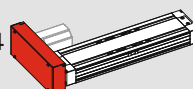
02



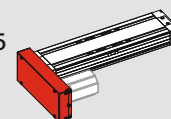
03



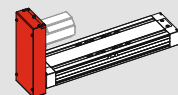
04



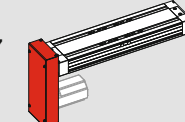
05



06



07



# COMPACT UNITS WITH BALL SCREW DRIVE



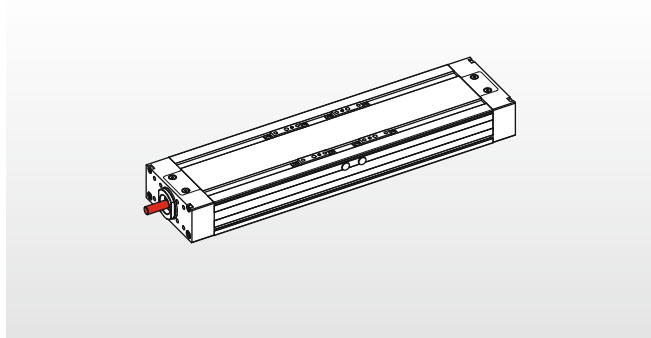
## Information for selection » Motor mounting preparation

### Motor fitting preparation – delivery conditions with ball screw drive

LINE TECH compact units with ball screw drive can be ordered in various delivery conditions in preparation for motor mounting. Dimensions see pages [36/37](#).

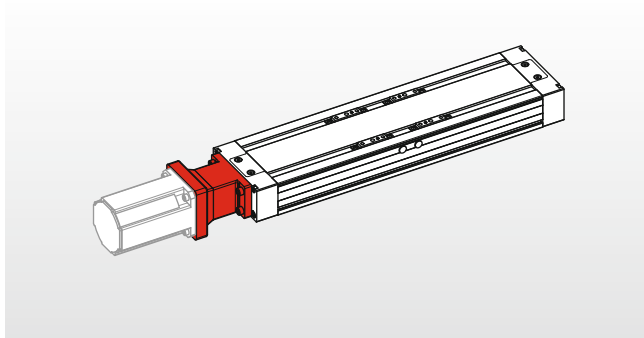
#### Delivery condition 01

Free spindle end



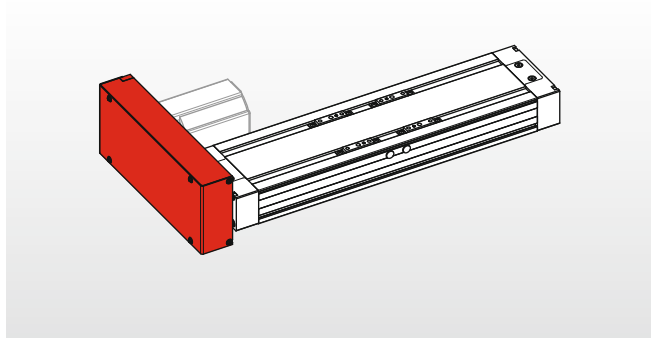
#### Delivery condition 02

With coupling and intermediate plate



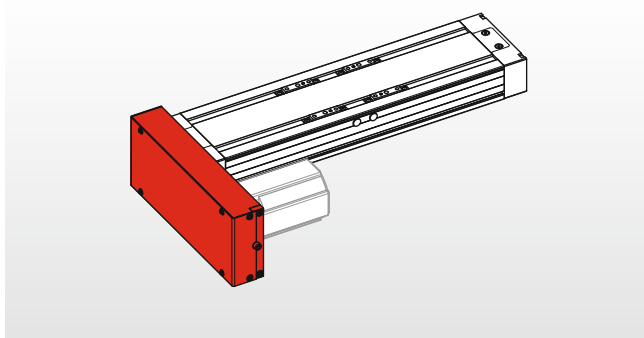
#### Delivery condition 04

Belt drive housing for side motor mounting right\*



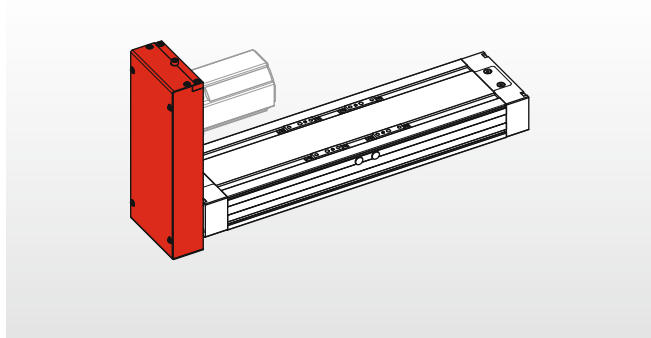
#### Delivery condition 05

Belt drive housing for side motor mounting left\*



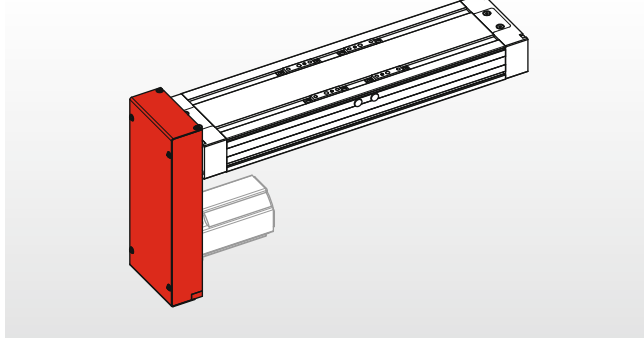
#### Delivery condition 06

Belt drive housing for lateral motor mounting top



#### Delivery condition 07

Belt drive housing for lateral motor mounting bottom



\* seen from motor opposite side towards motor

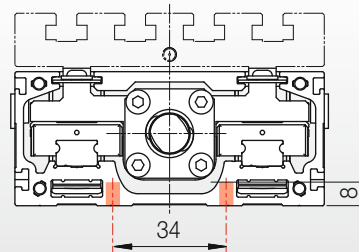


## COMPACT UNIT WITH BALL SCREW DRIVE



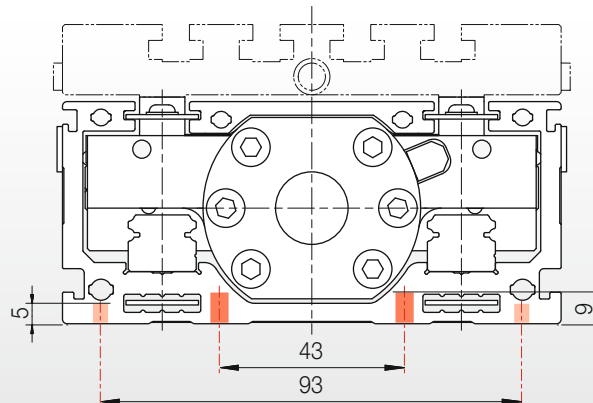
Areas for optional additional threads or holes in the base profile \*

KE1...R...



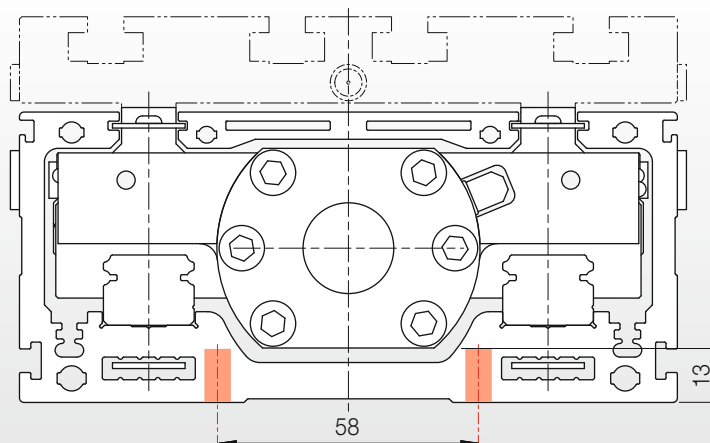
Positions for optional threaded holes  $\leq M4 \times 8$  mm or positioning holes  $\leq \varnothing 4 \times 8$  mm

KE2...R...



Positions for optional threaded holes  $\leq M5 \times 9$  mm or positioning holes  $\leq \varnothing 5 \times 9$  mm  
Positions for optional threaded holes  $\leq M4 \times 5$  mm or positioning holes  $\leq \varnothing 4 \times 5$  mm

KE3...R...



Positions for optional threaded holes  $\leq M6 \times 13$  mm or positioning holes  $\leq \varnothing 6 \times 13$  mm

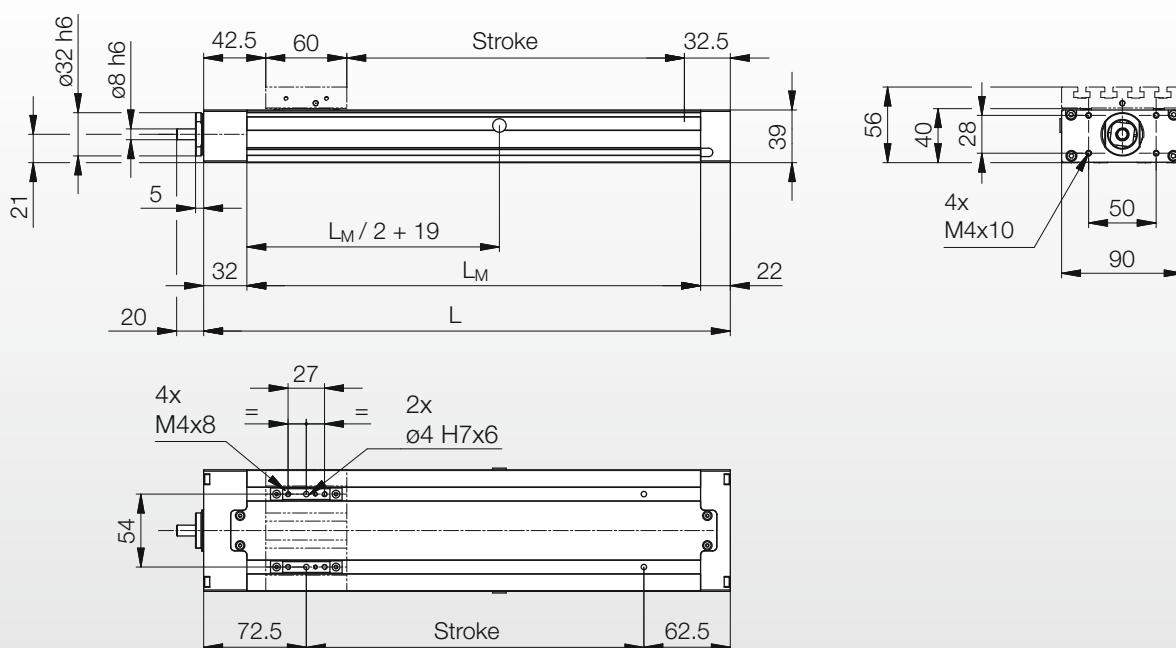
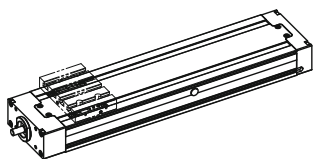
\* along the entire profile length  $L_M$ , see pages [20–25](#)



## COMPACT UNIT KE1.2...R...



with 1 carriage and ball screw drive



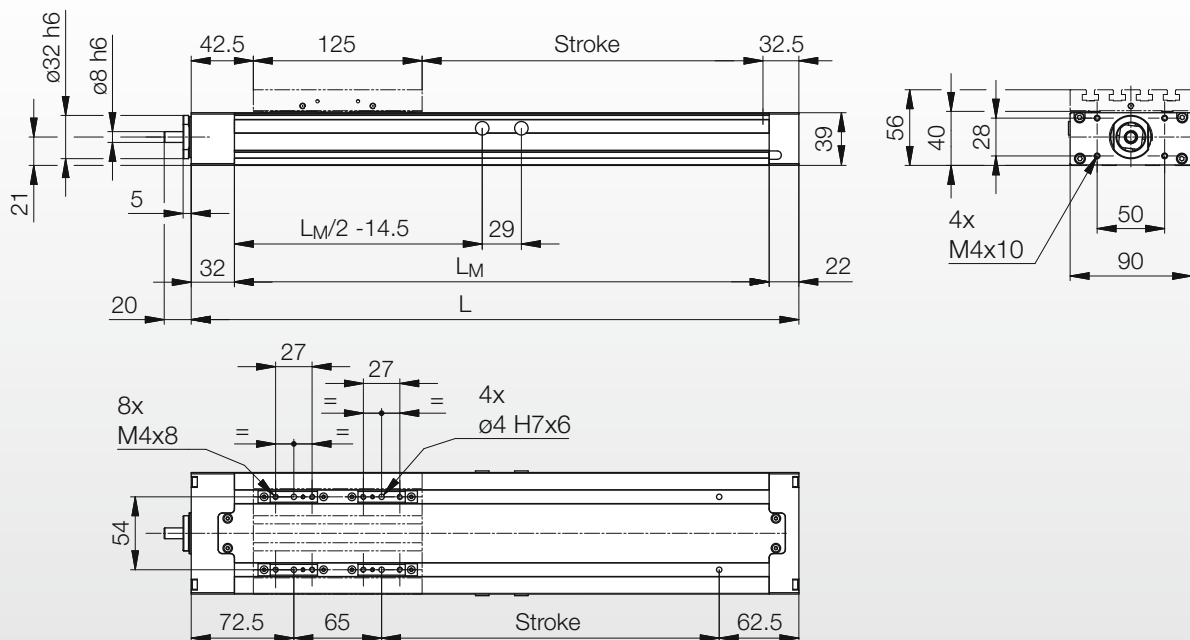
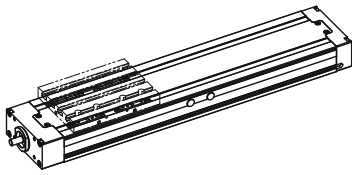
Nominal size	Dimensions				
Designation	L [mm]	$L_M$ [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE1.2...R...	Stroke + 135	$L - 54$	$L + 12$	$2 \times \text{Stroke} + 220$	$1.77 \text{ kg} + 0.410 \text{ kg/100 mm Stroke}$



## COMPACT UNIT KE1.4...R...



with 2 carriages and ball screw drive

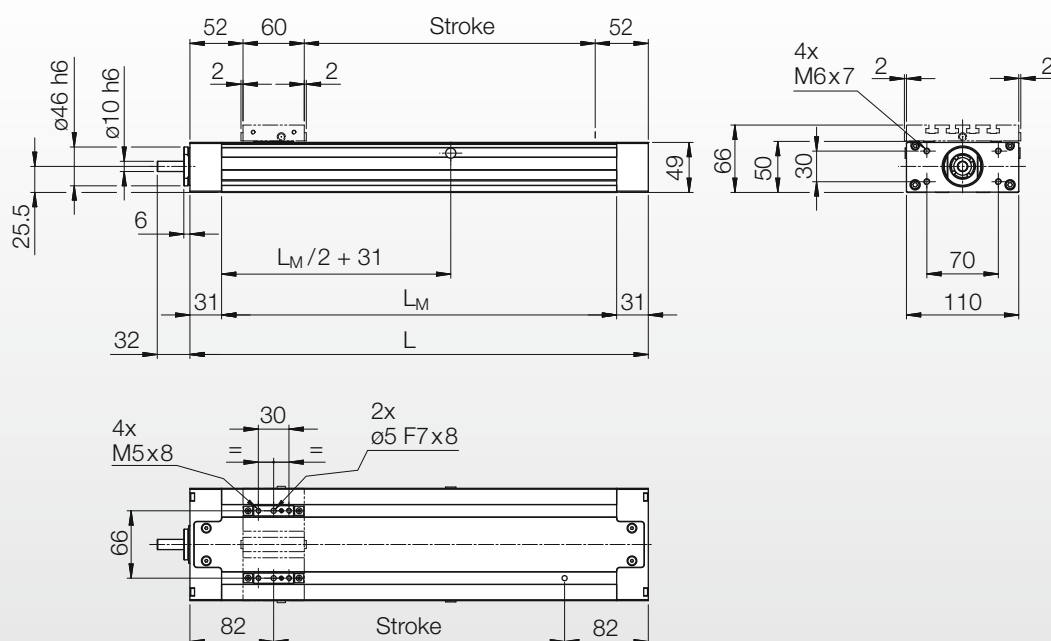
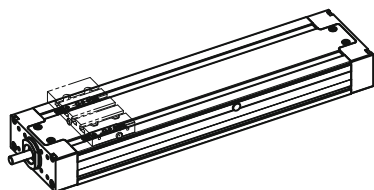


Nominal size	Dimensions				
Designation	L [mm]	$L_M$ [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE1.4...R...	Stroke + 200	$L - 54$	$L + 12$	$2 \times \text{Stroke} + 285$	$2.35 \text{ kg} + 0.410 \text{ kg/100 mm Stroke}$

## COMPACT UNIT KE2.2...R...



with 1 carriage and ball screw drive

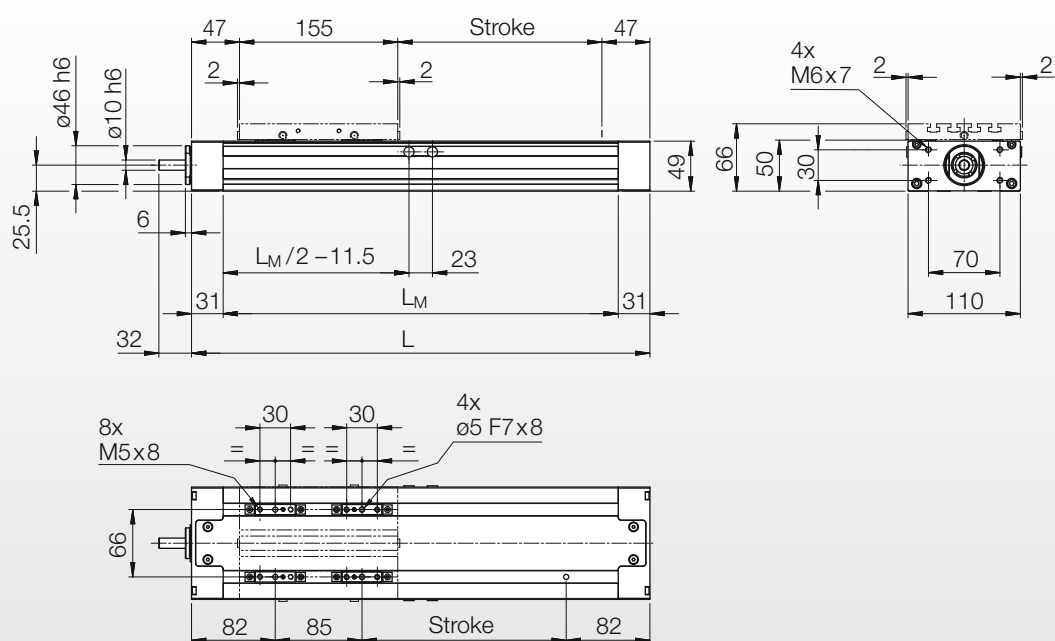
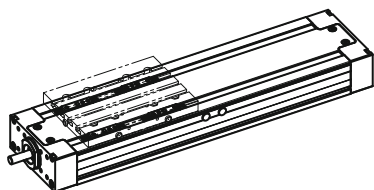


Nominal size	Dimensions				
Designation	L [mm]	L <sub>M</sub> [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE2.2...R...N	Stroke + 164	L - 62	L + 16	2 x Stroke + 294	1.90 kg + 0.852 kg/100 mm Stroke



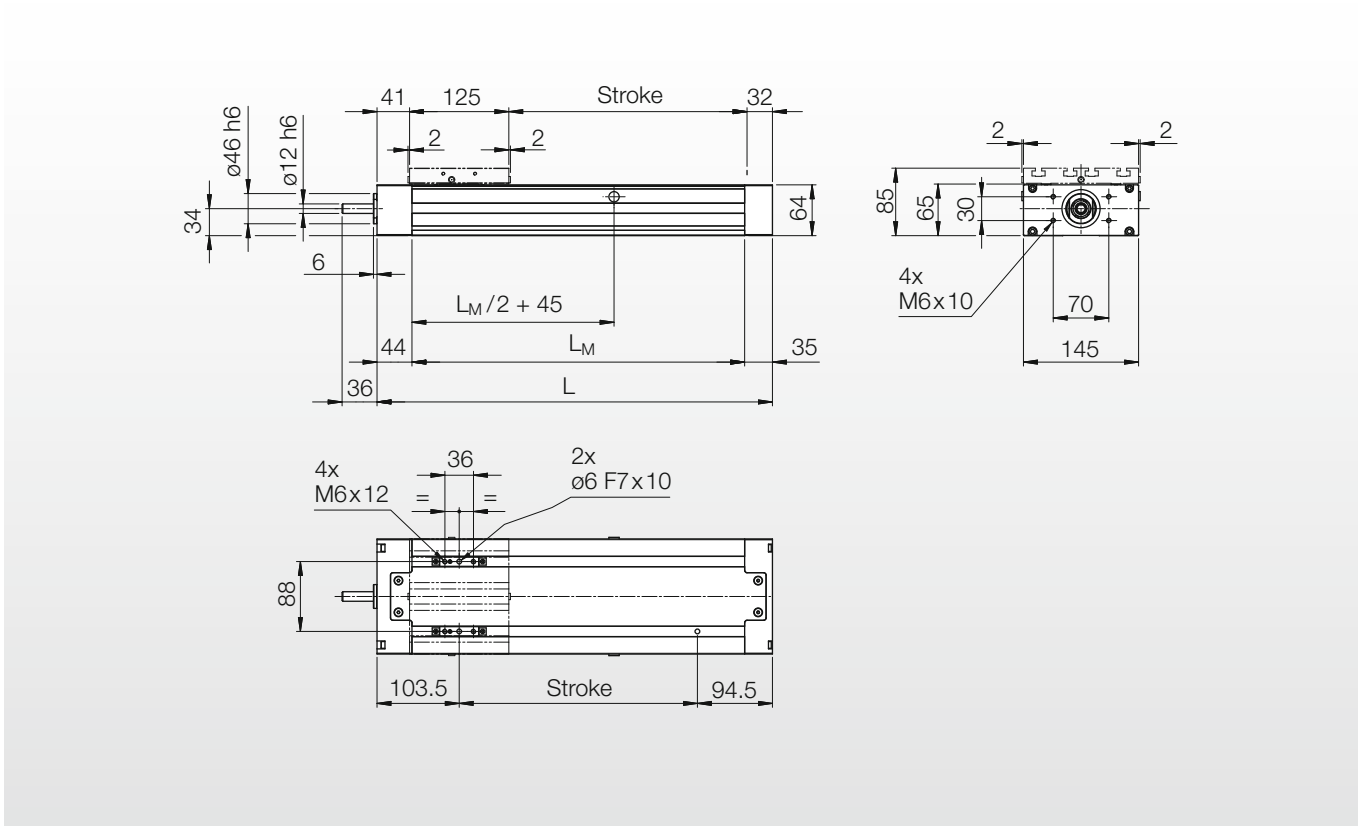
# COMPACT UNIT KE2.4...R...

with 2 carriages and ball screw drive



Nominal size	Dimensions				
Designation	L [mm]	L <sub>M</sub> [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE2.4...R...N	Stroke + 249	L - 62	L + 16	2 x Stroke + 379	3.25 kg + 0.852 kg/100 mm Stroke

A technical drawing of a linear guide assembly. It consists of a long, rectangular rail with a T-shaped cross-section. A carriage is mounted on the rail, featuring a central block with two mounting brackets on its sides. The drawing is a perspective view showing the top and side of the assembly.

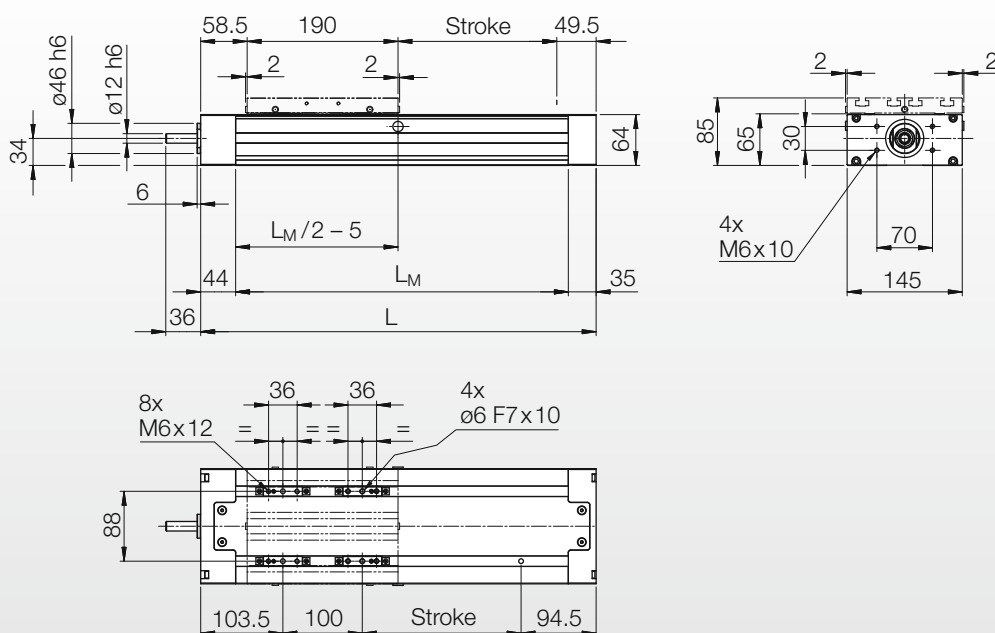
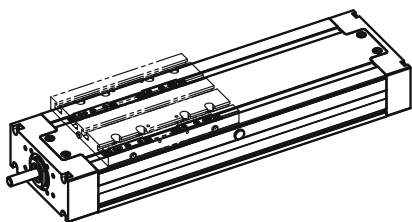


Nominal size	Dimensions				
Designation	L [mm]	L <sub>M</sub> [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE3.2...R...	Stroke + 198	L – 79	L + 17	2 x Stroke + 354	5.40 kg + 1.232 kg/100 mm Stroke



## COMPACT UNIT KE3.4...R...

with 2 carriages and ball screw drive



Nominal size	Dimensions				
Designation	L [mm]	$L_M$ [mm]	Length ball screw [mm]	Length protective ribbon [mm]	Weight [kg]
KE3.4...R...	Stroke + 298	$L - 79$	$L + 17$	$2 \times \text{Stroke} + 454$	$7.62 \text{ kg} + 1.232 \text{ kg}/100 \text{ mm Stroke}$

# COMPACT UNIT WITH TOOTHED BELT DRIVE



## Designation system

Compact unit (Designation example)


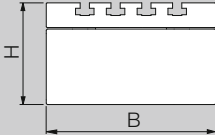
KE 2 . 2 . 0500 N Z 120 . 0 .

### Design

KE = Compact unit with linear rail guides

### Size (BxH)

2 = Size 110 mm

		
	KE... <b>N</b> ... B x H [mm]	KE... <b>V</b> ... B x H [mm]
Size		
2	110 x 50	110 x 66

### Configuration

2 = 2 runner blocks (short carriage)

4 = 4 runner blocks (long carriage)

### Stroke absolute [mm]

### Covering

N = without cover

### Drive

Z = Toothed belt drive

### Stroke per revolution [mm]

120 = Size 2 – toothed belt with 120 mm stroke per revolution

### Limit switches (see pages [34](#))

0 = without limit switches

1 = with 2 limit switches with plain-end cable (L = 2.0 m)

2 = with 2 limit switches with connector plug M8

3 = with 3 limit switches with plain-end cable (L = 2.0 m), reference switch at front (motor side) \*\*

4 = with 3 limit switches with plain-end cable (L = 2.0 m), reference switch at rear (opposite motor side) \*\*

\* View towards motor from the opposite side

\*\* Possible only with limit switch versions with plain-end cable

\*\*\* Standard version





12 . 0 N - N N N N N

5 8 4 - - —▶ 584... = Drawing type

#### Buffers

N = with integrated buffers

#### Limit switch installation position (see page 34)

N = without limit switch

L = left \*

R = right \*

#### Gearbox mounting (see page 30)

N = without connecting plate

D = top / rear

E = top / front

F = rear / bottom

G = rear / top

H = front / top

K = front / bottom

L = bottom / front

M = bottom / rear

#### Drive shaft

N = Standard drive shaft \*\*\*

H = Shaft for angular gearbox HPG030

S = Shaft for angular gearbox HPG045

#### Connecting plate (see pages 42/43)

N = without connecting plate \*\*\*

V = with connecting plate

#### Motor mounting

N = without motor mount \*\*\*

F = Connecting plate for standard motor

S = Connecting plate for special motor

#### Gear ratio (for available gear ratios HPG030/HPG045 see page 39)

0 = none (without gearbox)

X =  $i = 1 : \text{_____}$  (gear ratio)

#### Delivery condition (see pages 28/29)

11 = Free shaft end right \*

12 = Free shaft end left \*

13 = Shaft end right with coupling and intermediate flange \*

14 = Shaft end left with coupling and intermediate flange \*

17 = Free shaft ends on both sides (continuous shaft)

18 = Shaft end on both sides, with coupling and intermediate flange on right \*

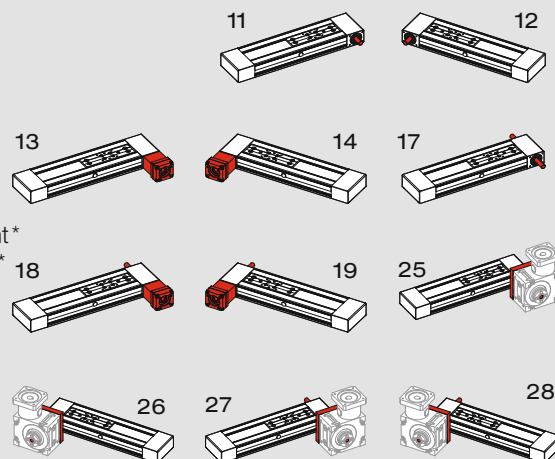
19 = Shaft end on both sides, with coupling and intermediate flange on left \*

25 = Shaft end right with gearbox connecting plate \*

26 = Left shaft end with gearbox connecting plate \*

27 = Shaft end on both sides, with gearbox connecting plate on the right \*

28 = Shaft end on both sides, with gearbox connecting plate on the left \*



# COMPACT UNIT WITH TOOTHED BELT DRIVE



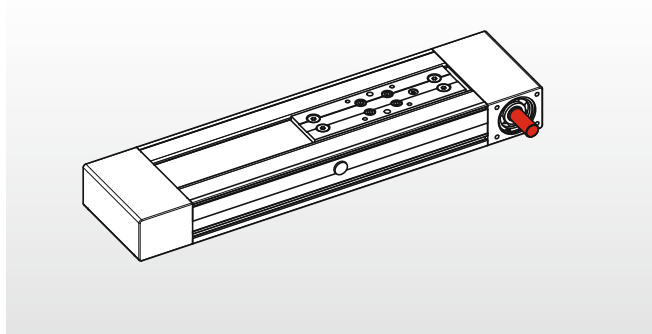
## Notes on selection » Preparation for motor mounting (1/3)

### Preparation for motor mounting – delivery conditions with toothed belt drive

LINE TECH compact units with toothed belt drive can be ordered in various delivery conditions in preparation for motor mounting. For dimensions, see pages [38/39](#).

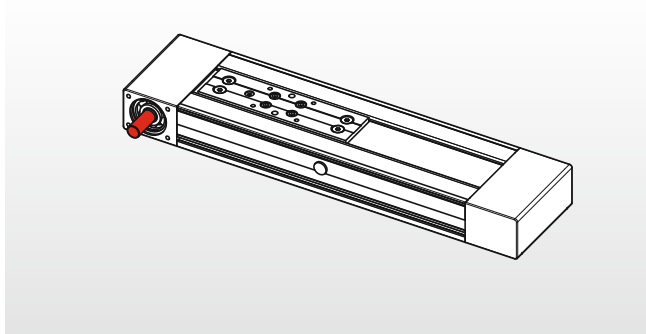
#### Delivery condition 11

Free shaft end on right \*



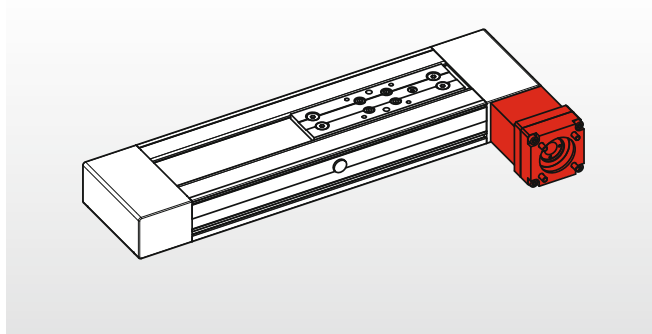
#### Delivery condition 12

Free shaft end on left \*



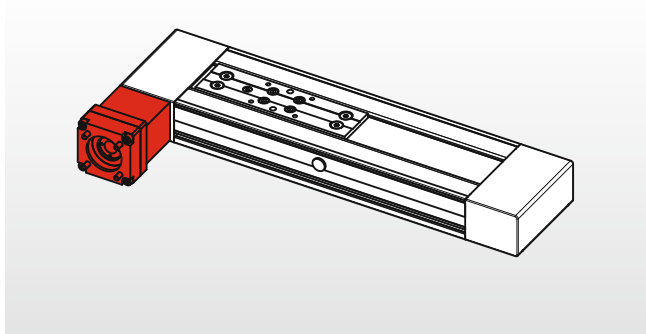
#### Delivery condition 13

Shaft end on right\* with coupling and motor flange



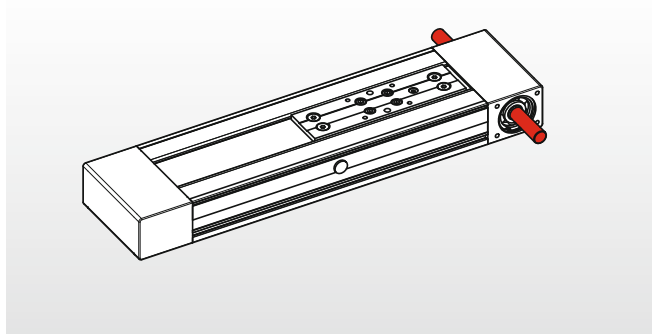
#### Delivery condition 14

Shaft end on left\* with coupling and motor flange



#### Delivery condition 17

Free shaft ends on both sides



\* View towards motor from the opposite side



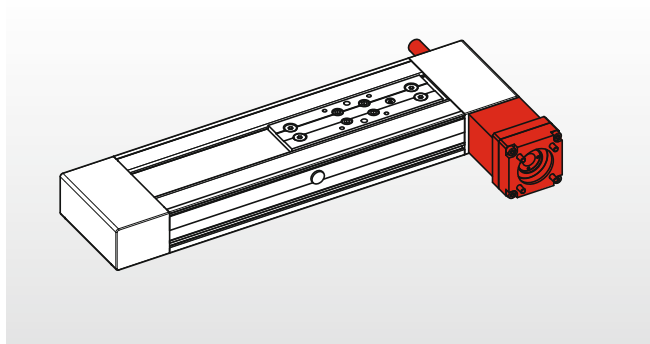
## COMPACT UNIT WITH TOOTHED BELT DRIVE



### Notes on selection » Preparation for motor mounting (2/3)

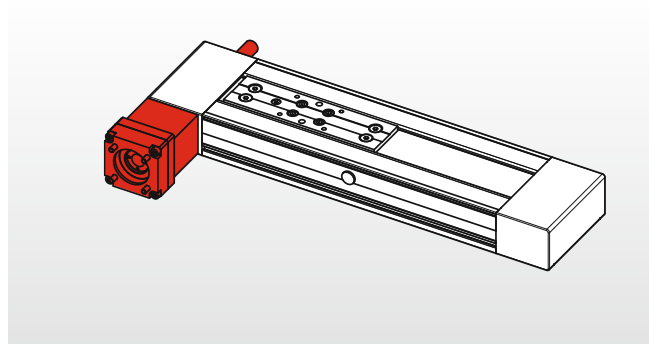
#### Delivery condition 18

Shaft ends on both sides, right\* with coupling and motor flange



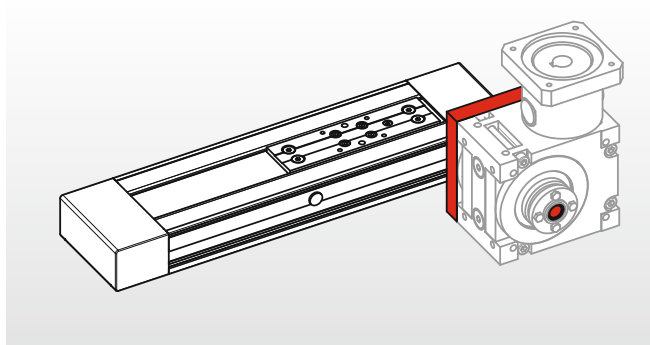
#### Delivery condition 19

Shaft ends on both sides, left\* with coupling and motor flange



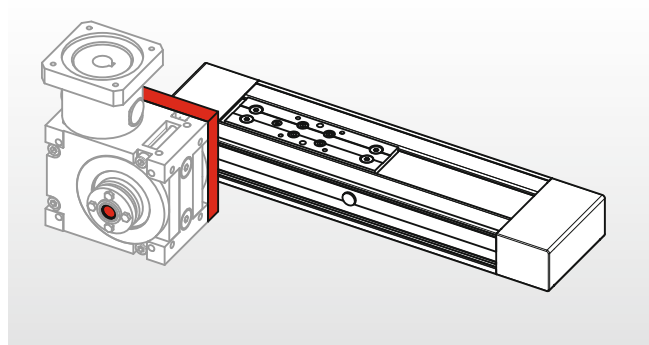
#### Delivery condition 25

Shaft end on right\* with gearbox connecting plate



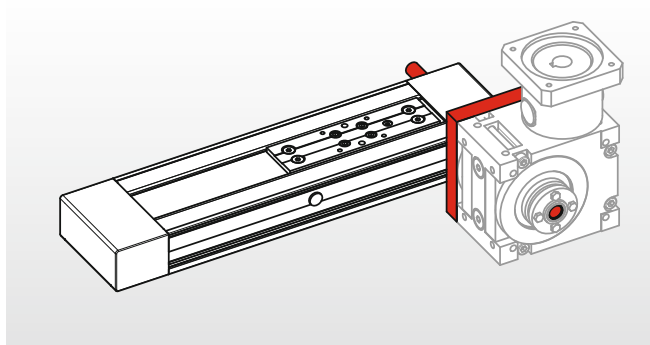
#### Delivery condition 26

Shaft end on left\* with gearbox connecting plate



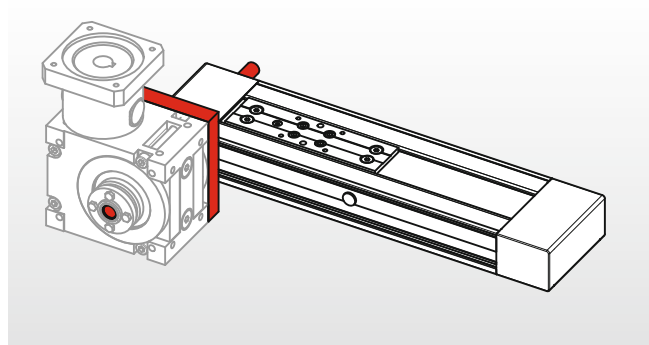
#### Delivery condition 27

Shaft ends on both sides, right\* with gearbox connecting plate



#### Delivery condition 28

Shaft ends on both sides, left\* with gearbox connecting plate



\* View towards motor from the opposite side



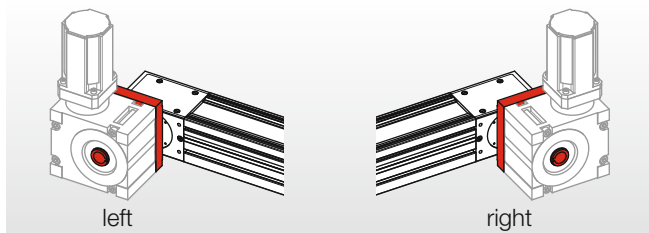
## Notes on selection » Preparation for motor mounting (3/3)

### Preparation for motor mounting – Mounting options (orientation) of angular gearboxes

For delivery conditions 25 to 28 (see page [29](#)), the gearbox connecting plate can be pre-assembled in different ways depending on the desired gearbox mounting or motor position:

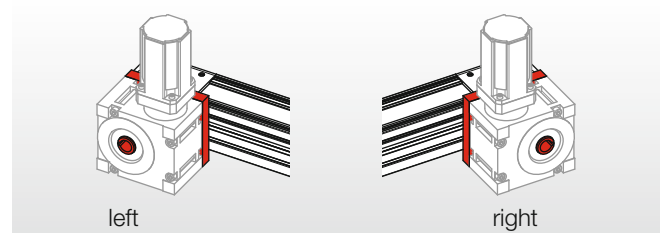
#### Gearbox mounting D

Gearbox mounted rear\* and top



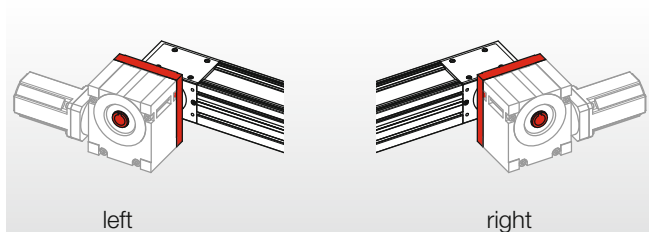
#### Gearbox mounting E

Gearbox mounted front\* and top



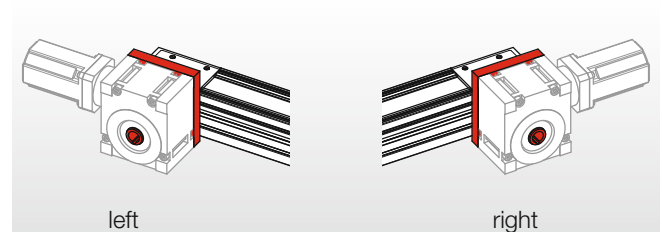
#### Gearbox mounting F

Gearbox mounted rear\* and bottom



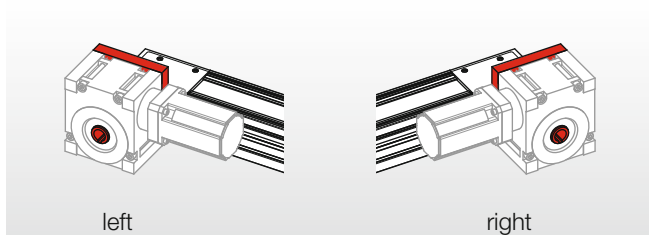
#### Gearbox mounting G

Gearbox mounted rear\* and top



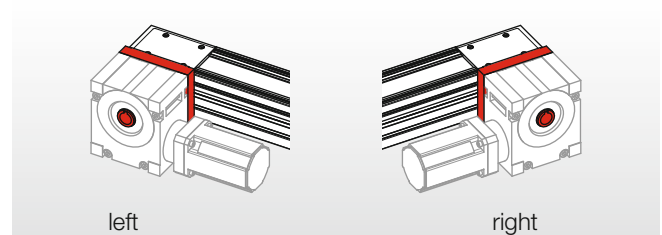
#### Gearbox mounting H

Gearbox mounted front\* and top



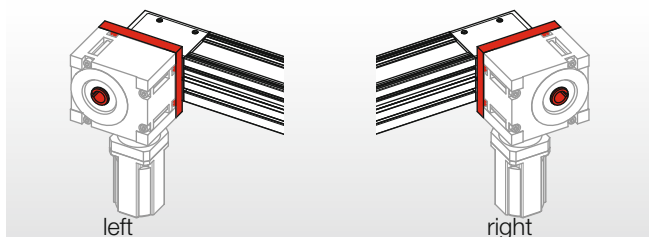
#### Gearbox mounting K

Gearbox mounted front\* and bottom



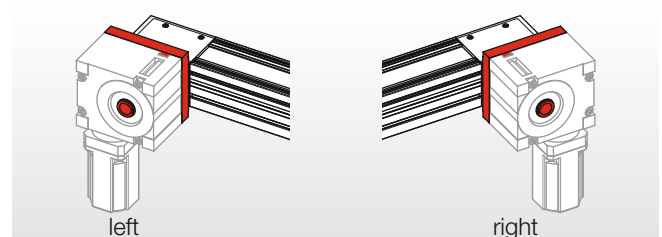
#### Gearbox mounting L

Gearbox mounted front\* and bottom



#### Gearbox mounting M

Gearbox mounted rear\* and bottom



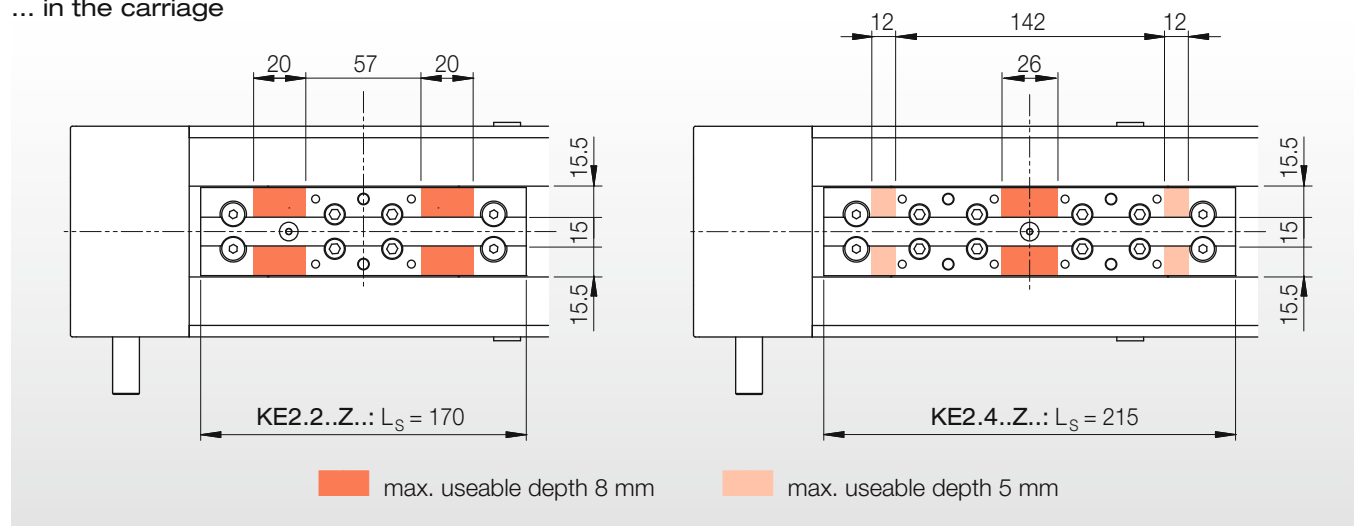
\* View towards motor from the opposite side

## COMPACT UNIT WITH TOOTHED BELT DRIVE

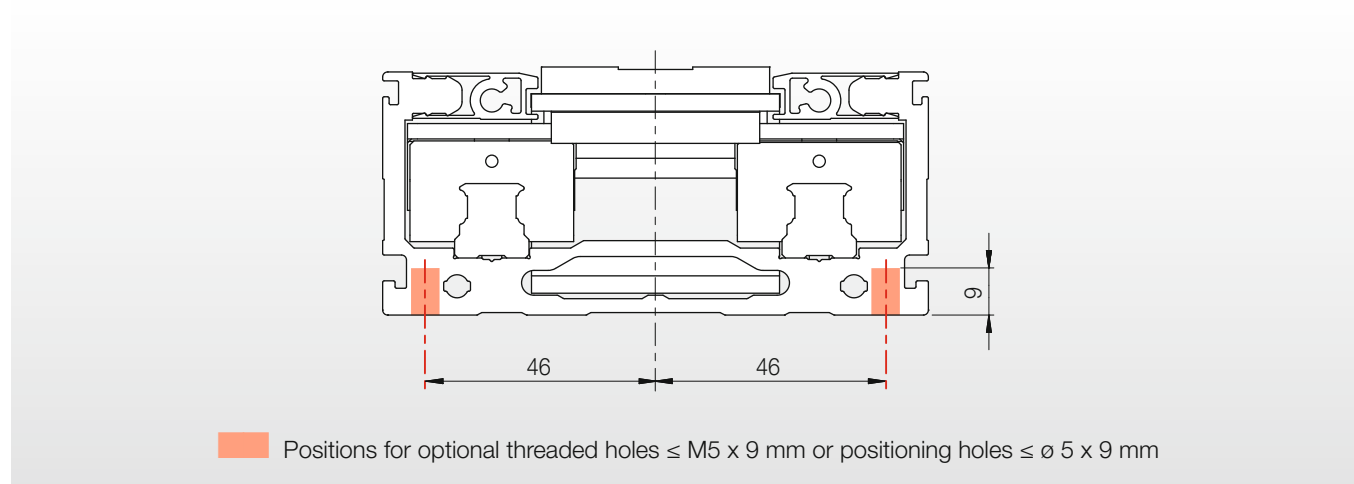


Areas for optional additional threads or holes ...

... in the carriage



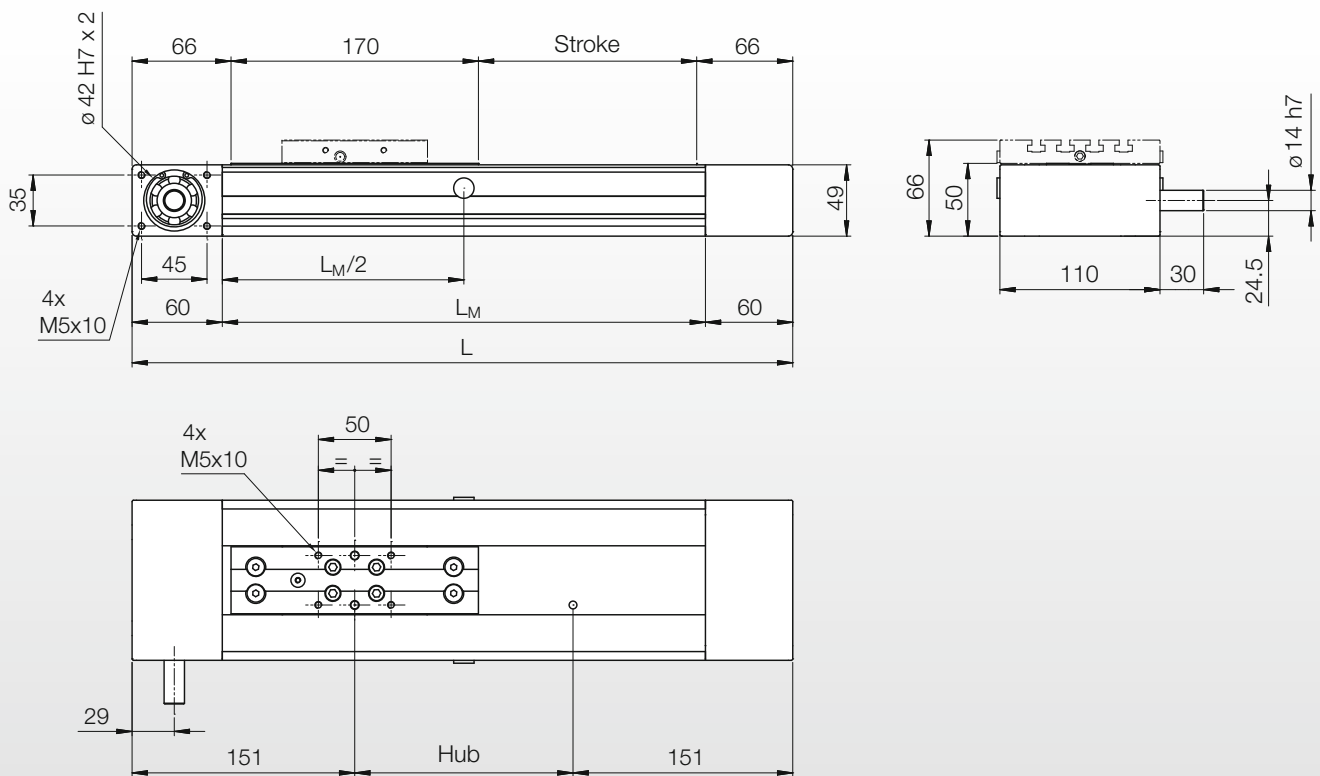
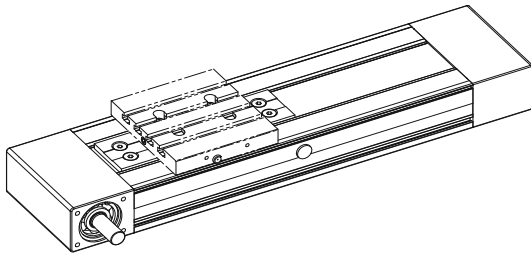
... in the base profile (along the entire profile length  $L_M$ , see pages [32/33](#))



## COMPACT UNIT KE2.2...Z...



with 2 runner blocks (short carriage) and toothed belt drive



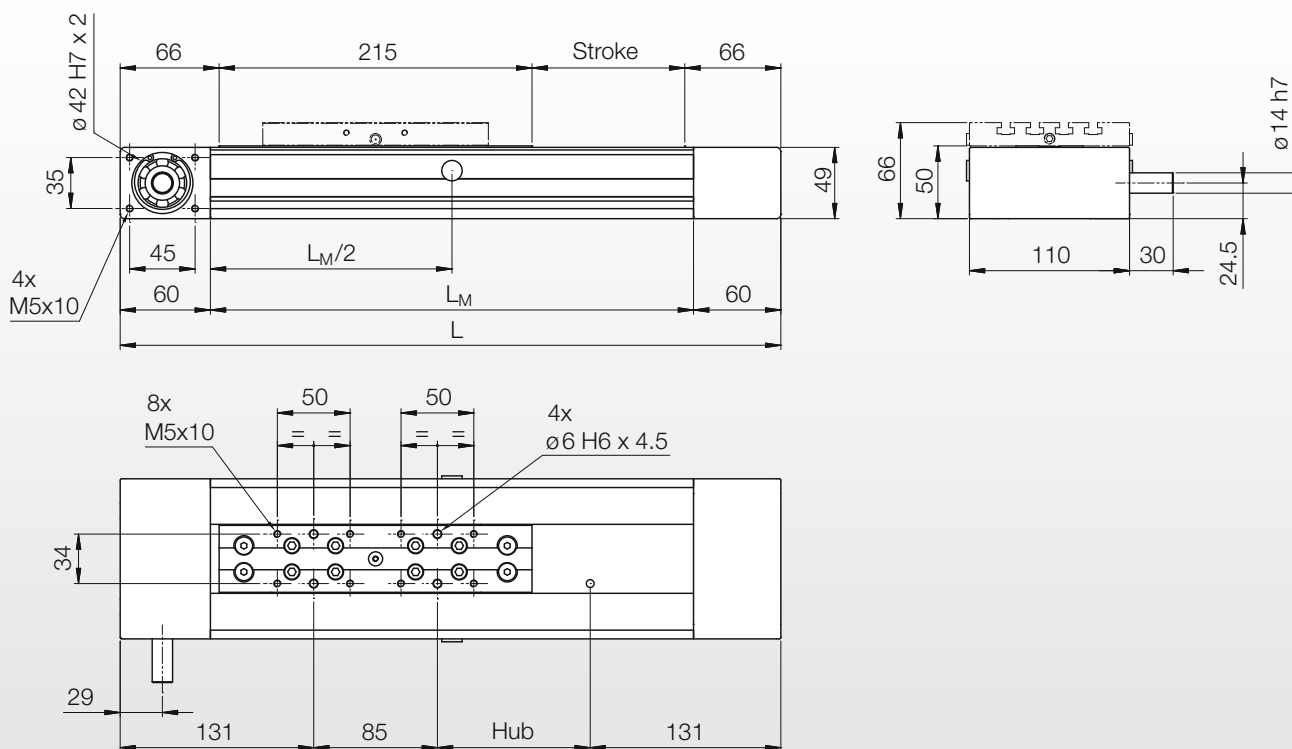
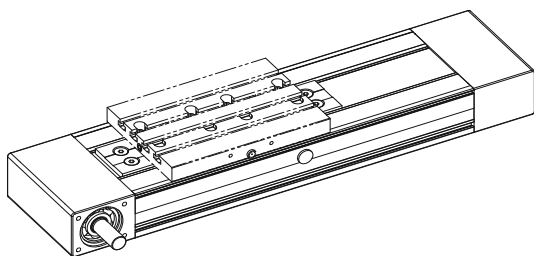
Nominal size	Dimensions			
Designation	L [mm]	L <sub>M</sub> [mm]	Belt length [mm]	Weight [kg]
KE2.2...Z...	Stroke + 302	L – 120	2 x Stroke + 480	4.12 kg + 0.720 kg/100 mm Stroke





## COMPACT UNIT KE2.4...Z...

with 4 runner blocks (long carriage) and toothed belt drive



Nominal size	Dimensions			
Designation	L [mm]	L <sub>M</sub> [mm]	Belt length [mm]	Weight [kg]
KE2.4...Z...	Stroke + 347	L – 120	2 x Stroke + 535	5.22 kg + 0.720 kg/100 mm Stroke

## Limit switch installation; for all drive types

### Limit switches

Operated in conjunction with a control unit, limit switches are necessary to limit the stroke (prevent carriage overshoot) and to establish a reference point for setting the zero point.

LINE TECH uses the following inductive limit switches as standard

- PNP opener (PNP-NC)

Power supply: 6...36 V DC

Power consumption with no load:

<12 mA

Load: max. 200 mA

The following limit switches are also available on request:

- PNP opener (PNP-NC)
- PNP closer (PNP-NO)
- NPN opener (NPN-NC)
- NPN closer (NPN-NO)

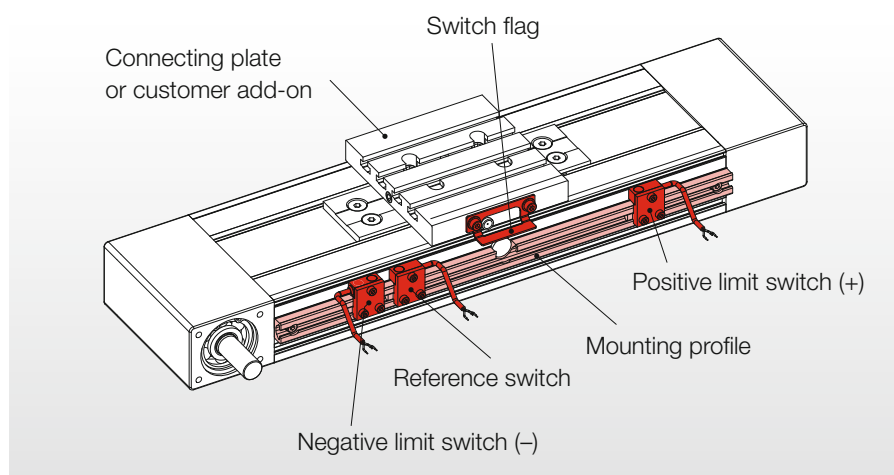
**Note:** The positive and negative limit switches are preset at the factory to a nominal stroke of 0 to +5 mm.

### Installation position of the limit switches

Installation positions of the limit switches are shown in the following illustrations. The reference point can be assigned to the positive (+) or negative (–) limit switch.

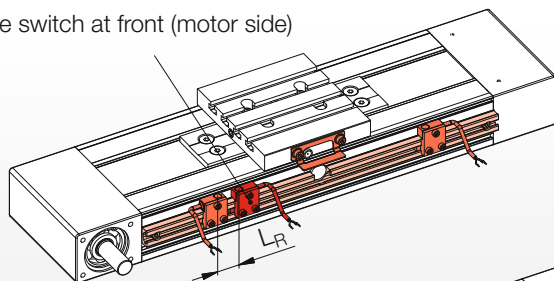
Special applications often require a separate reference-point switch mounted between the positive and negative limit switches. We refer to the limit switch that is closer to the motor mount (limit switch-control interface) as the front limit switch.

### Overview of limit switch/reference switch mounting



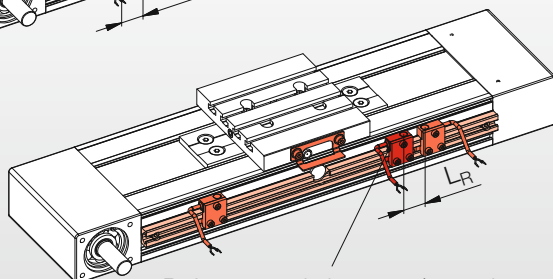
### Position of reference switch ( $L_R$ )

Reference switch at front (motor side)



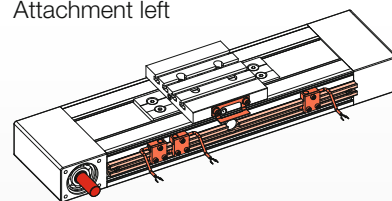
$L_R = 20 \text{ mm}$

Reference switch at rear (opposite motor side)

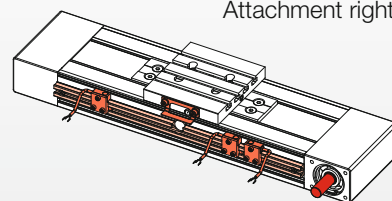


### Limit switch installation

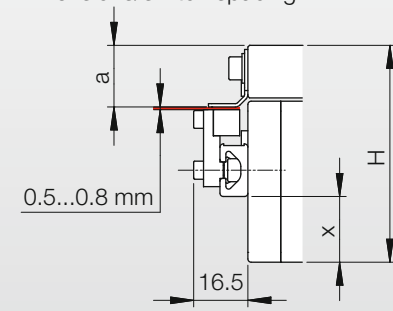
Attachment left



Attachment right



Dimensions/switch spacing:



Size	Dimensions [mm]		
	x	a	H
KE1...R	3	17.5	56
KE2...R	13	17	66
KE2...Z	20	18.7	66
KE3...R	32.5	17	85

## COMPACT UNITS

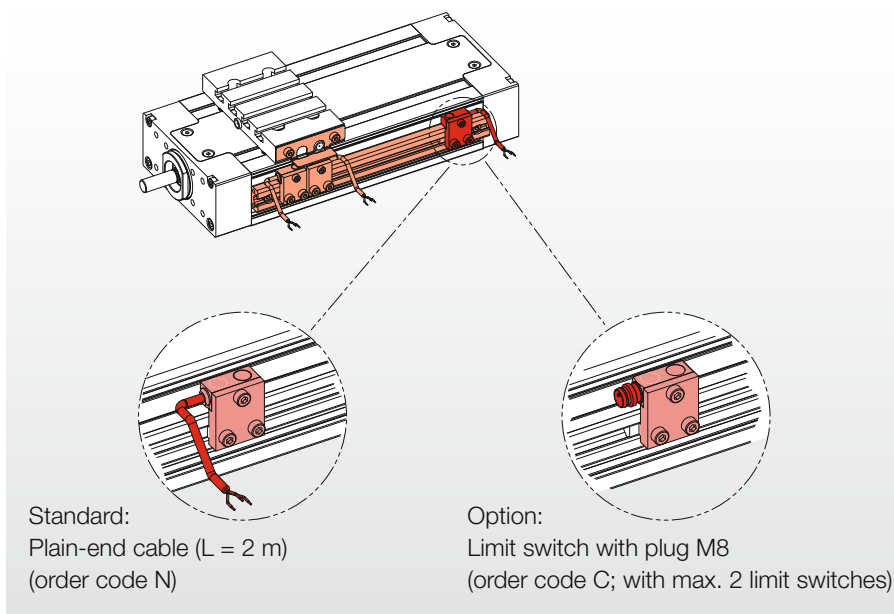


### Limit switch design; for all drive types

#### Limit switch design KE1/2/3...R...

Limit switches are supplied with plain-end cables (length 2 m) as standard (order code N).

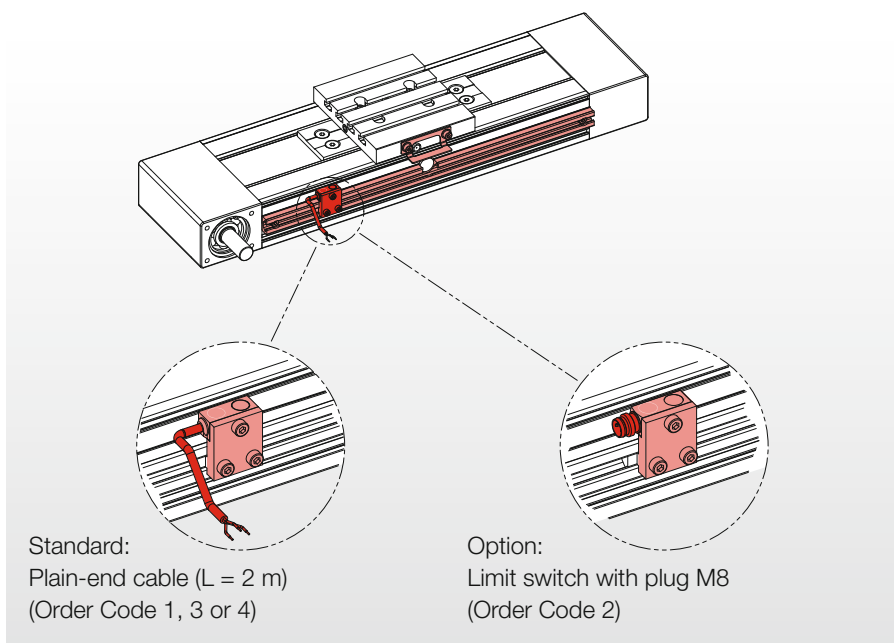
As an option, the limit switches can also be supplied with an M8 connector plug (order code C; with max. 2 limit switches).



#### Limit switch design KE2...Z...

Limit switches are supplied with plain-end cables (length 2 m) as standard (Order Code 1, 3 or 4).

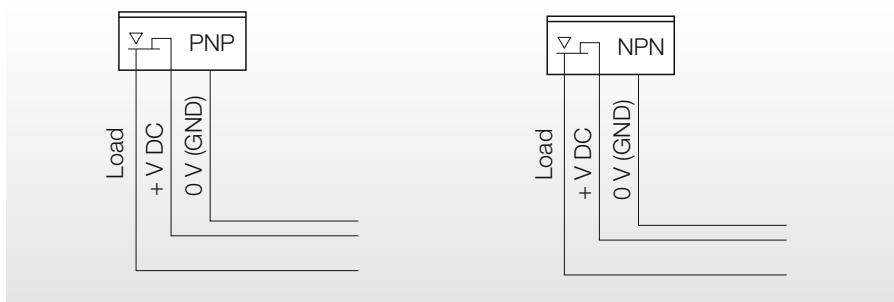
As an option, the limit switches can also be supplied with an M8 connector plug (Order Code 2).



#### Limit switch wiring diagram

Colour code legend for the adjacent diagrams:

Load = black (BK)  
 +V DC = brown (BN)  
 0 V (GND) = blue (BU)

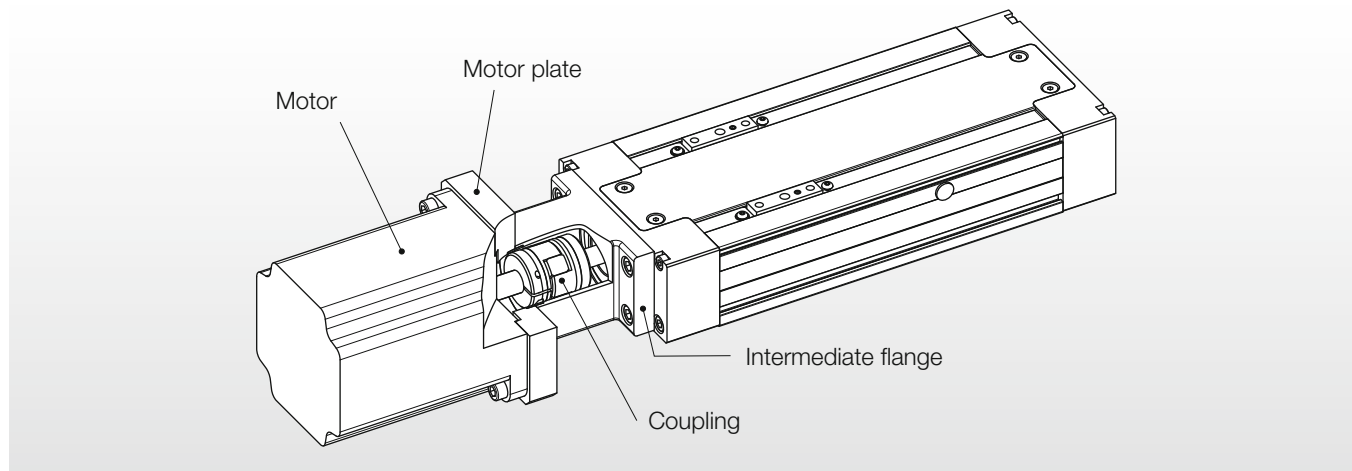


# COMPACT UNITS WITH BALL SCREW DRIVE

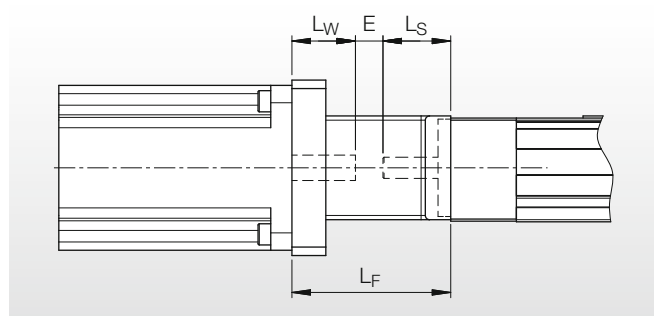


Dimensions for motor mounting; straight fit

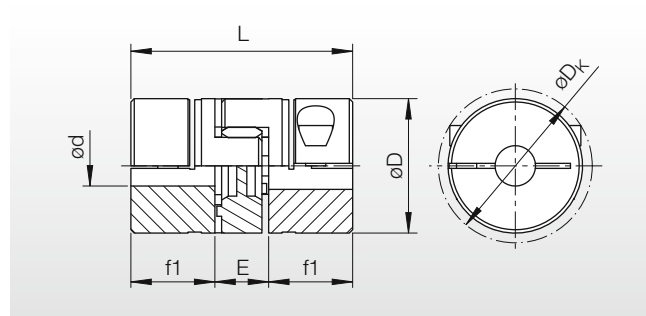
Straight motor mounting



Length of motor mounting



Coupling

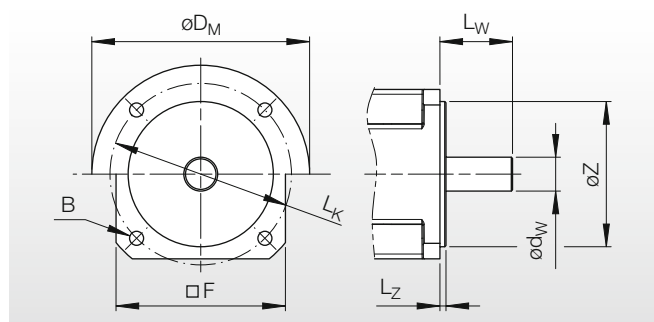


Nominal size	Dimensions			Coupling
	$L_F \pm 2$ [mm]	$L_S$ [mm]	Weight * [kg]	
KE1...R...	$L_S + E + L_W$	20	0.350	Size 12
KE2...R...		32	0.500	Size 14
KE2...R...		32	0.580	Size 19
KE3...R...		36	0.640	Size 19

Dimensions [mm]							Drive torque [Nm]	
Size	L	$\phi D$	$\phi d$	f1	E	$\phi D_K$	$T_N$	$T_{max}$
12	34	25	$\leq 12$	11	12	27.5	5.0	18
14	35	30	$\leq 16$	11	13	32.2	6.3	25
19	66	40	$\leq 20$	25	16	43	17	34

\* flange including coupling

Motor dimensions \*\*



\*\* the following dimensions are required to determine the motor mounting:

$\phi D_M$	_____ [mm]	$L_W$	_____ [mm]
$B$	_____ [mm]	$\phi d_W$	_____ [mm]
$\square F$	_____ [mm]	$L_Z$	_____ [mm]
$L_K$	_____ [mm]	$\phi Z$	_____ [mm]

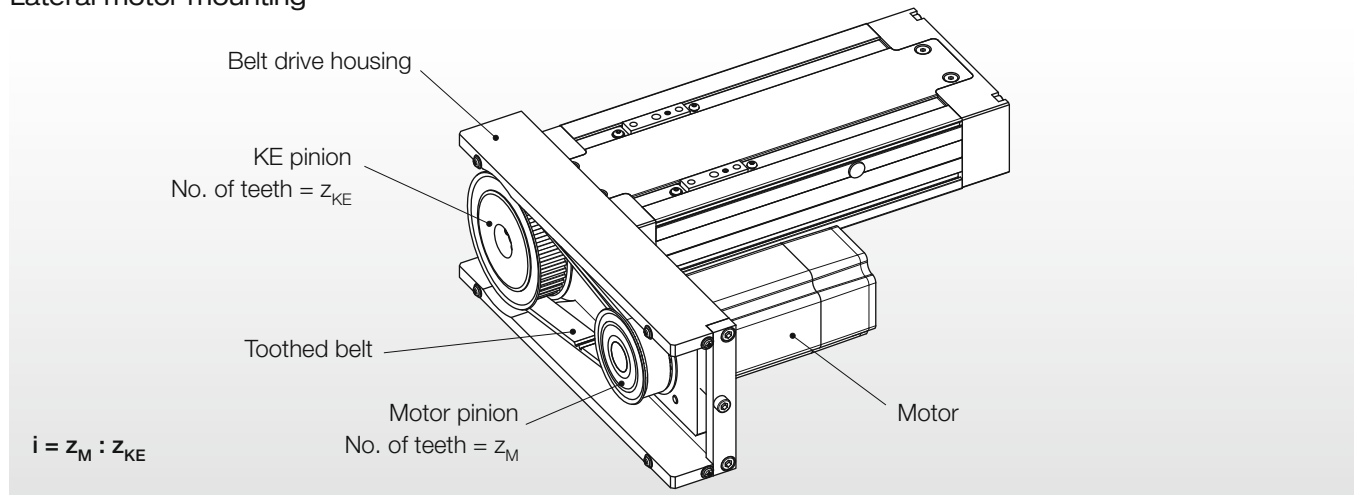


# COMPACT UNITS WITH BALL SCREW DRIVE

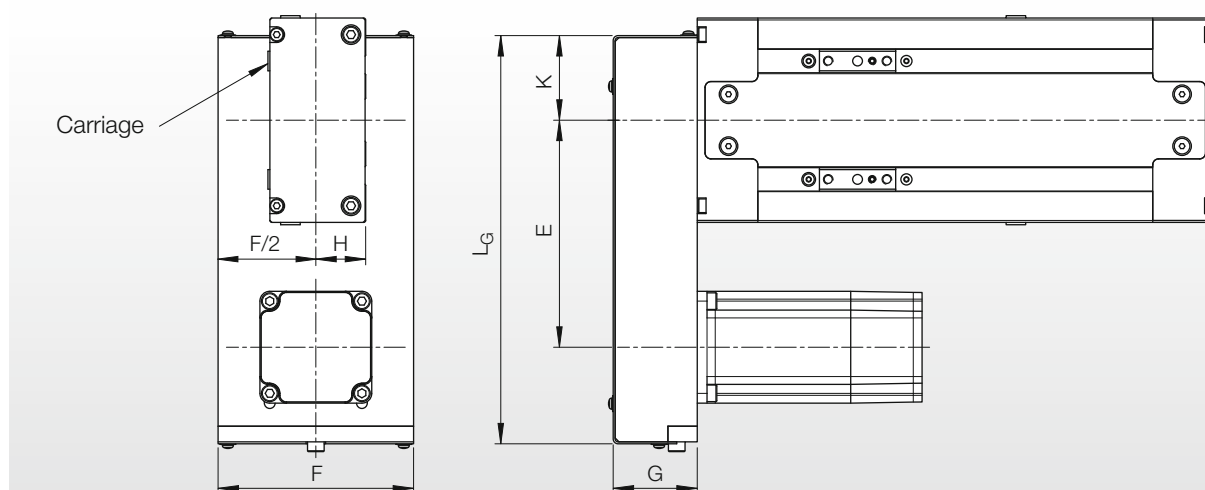


## Dimensions for motor mounting; lateral fit

### Lateral motor mounting



### Dimensions for lateral motor mounting



Nominal size	Dimensions [mm]							No. of teeth		Max.	Belt length	Weight
	i	E	F	G*	H	K	L <sub>G</sub>	z <sub>M</sub>	z <sub>KE</sub>	ø d <sub>W</sub>	[mm]	[kg]
KE1...R...	1:1	90.5...104 (92.5)						28	28	ø16	325	0.860
	1:1.5	90.5...104 (99.4)	80	41	21	39	180	28	42	ø16	375	0.990
	1:2	90.5...104 (94.8)						21	42	ø10	350	0.980
KE2...R...	1:1	130...135 (132.5)						32	32	ø19	425	1.600
	1:1.5	131...139 (136.9)	100	43	43	46	247	32	48	ø19	475	1.800
	1:2	131.5...135.5 (133.6)						24	48	ø12	450	1.700
KE3...R...	1:1	130...135 (132.5)						32	32	ø19	425	1.600
	1:1.5	131...139 (136.9)	100	43	54	46	247	32	48	ø19	475	1.800
	1:2	131.5...135.5 (133.6)						24	48	ø12	450	1.700

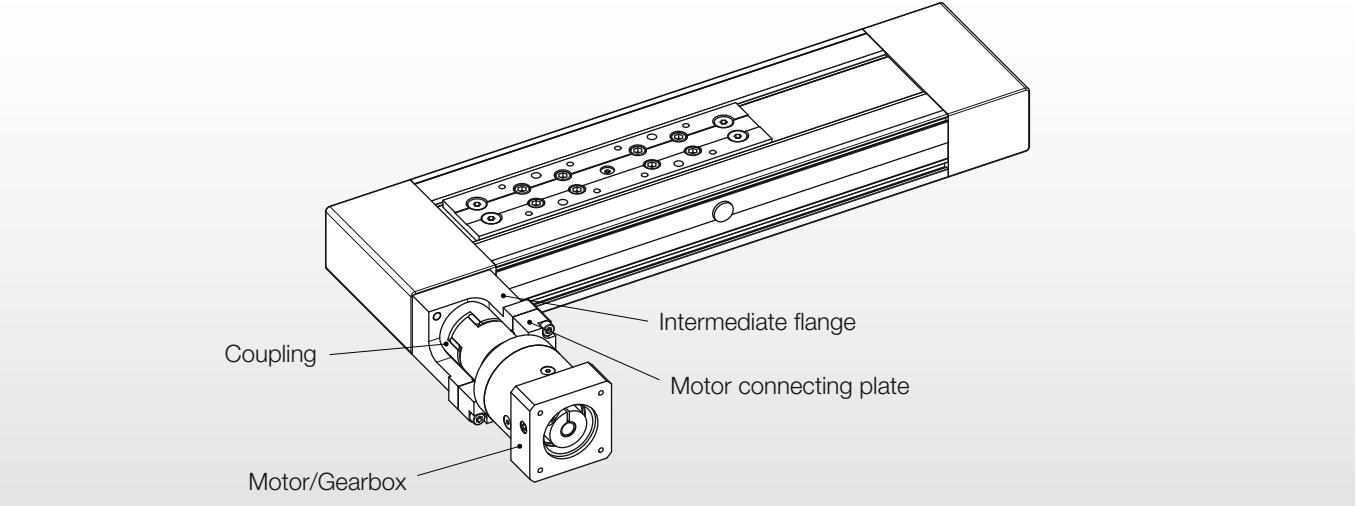




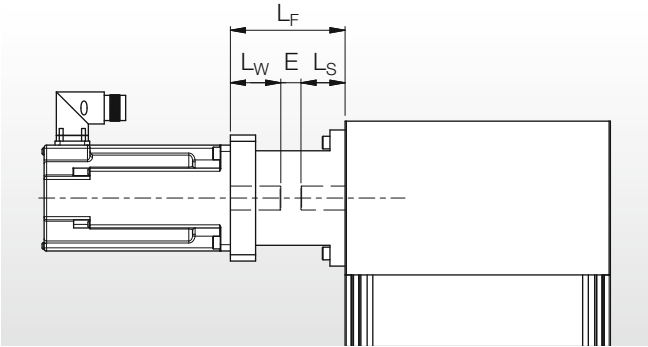
# COMPACT UNIT WITH TOOTHED BELT DRIVE

## Dimensions of mounted motor; straight attachment

### Straight motor attachment



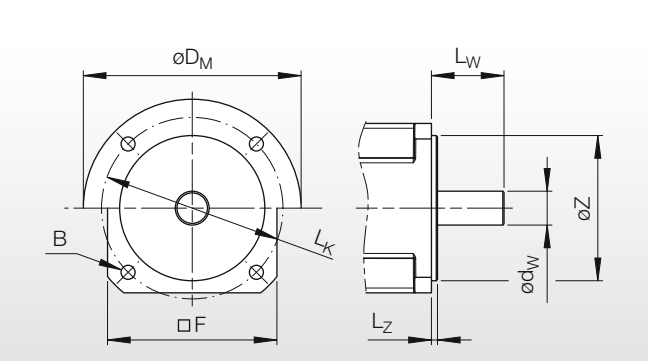
### Length of attached motor



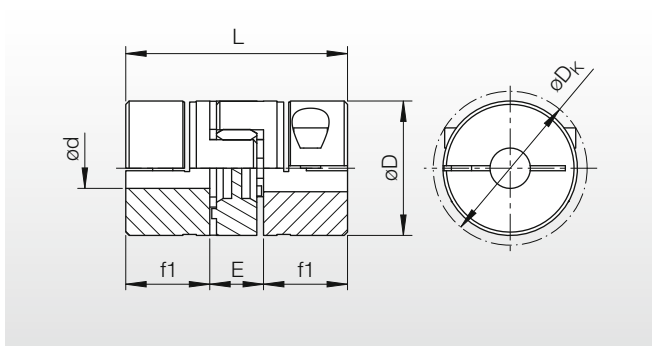
Nominal size	Dimensions		Weight * [kg]	Coupling if $L_W > f_1$
	$L_F \pm 2$ [mm]	$L_S$ [mm]		
KE2...Z... $L_S + E + L_W$		30	0.300	Size 14
		30	0.590	Size 19

\* Flange including coupling

### Motor dimensions \*\*



### Coupling



Dimensions [mm]							Drive torque [Nm]	
Size <sup>1)</sup>	L	ØD	Ød	f <sub>1</sub>	E	ØD <sub>K</sub>	T <sub>N</sub>	T <sub>max</sub>
14	35	30	≤ 16	11	13	32.2	6.3	25
19	66	40	≤ 20	25	16	40 <sup>2)</sup>	17	34

<sup>1)</sup> Depends on motor torque

<sup>2)</sup> Coupling with clamping ring hub required

\*\* Dimensions required for determining motor attachment:

ØD <sub>M</sub> _____ [mm]	L <sub>W</sub> _____ [mm]
B _____ [mm]	Ød <sub>W</sub> _____ [mm]
□ F _____ [mm]	L <sub>Z</sub> _____ [mm]
L <sub>K</sub> _____ [mm]	ØZ _____ [mm]
Motor torque max. _____ [Nm]	
Motor speed max. _____ [min <sup>-1</sup> ]	



# COMPACT UNIT WITH TOOTHED BELT DRIVE



## Dimensions of mounted motor; gearbox mounting

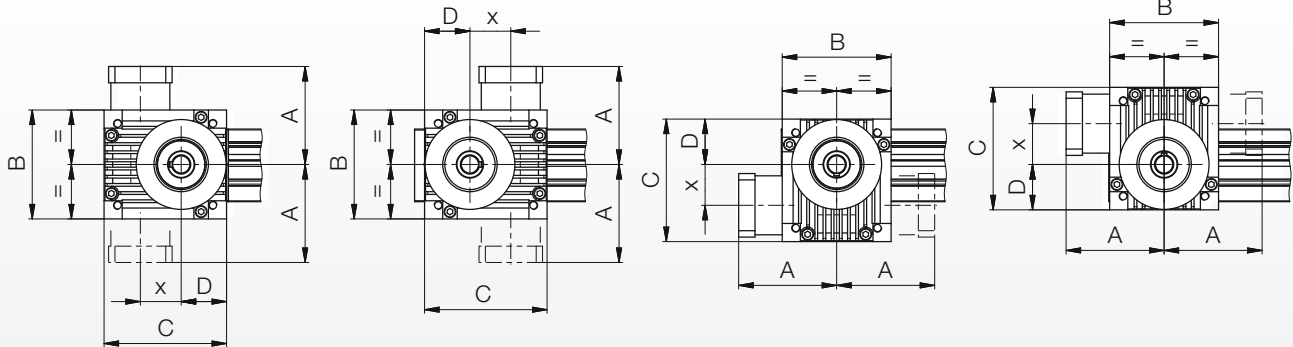
### Gearbox mounting dimensions

Mounting options: D + M

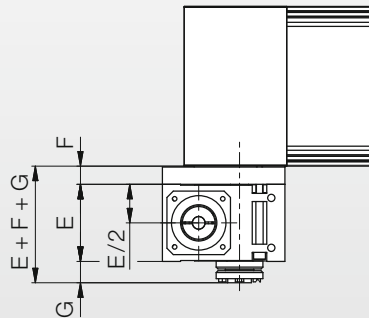
Mounting options: E + L

Mounting options: F + K

Mounting options: G + H



Mounting options see page 14



High-performance servo angular gearbox  
HPG030 or HPG045 <sup>1)</sup>

Nominal size	Gearbox type	Housing dimensions [mm]									Weight		Gearbox [kg]
		x	L <sub>w</sub>	A	B	C	D	E	F	G	[kg]		
KE2..Z...	HPG030	30	20...33	85	90	100	40	65	12	18.5	0.900		2.020
	HPG045 <sup>1)</sup>	45	20...33	98									4.100
		45	33...43	108	120	135	50	85	20	23.5	1.600		4.200

L<sub>w</sub> = Length of motor shaft (see page 38)

Gearbox type depends on torque and speed:

- HPG030: max. output torque on the gearbox journal 21 Nm
- HPG045: max. output torque on the gearbox journal 90 Nm
- HPG030 / HPG045: max. input speed 6000 min<sup>-1</sup>

Available gear ratios for both gearbox types: 1:2 / 3 / 4 / 5 / 6 / 8 / 10 / 13.33 / 16 / 24 / 30 / 47 / 60

<sup>1)</sup> when using the HPG045 gearbox, the customer must provide additional torque support



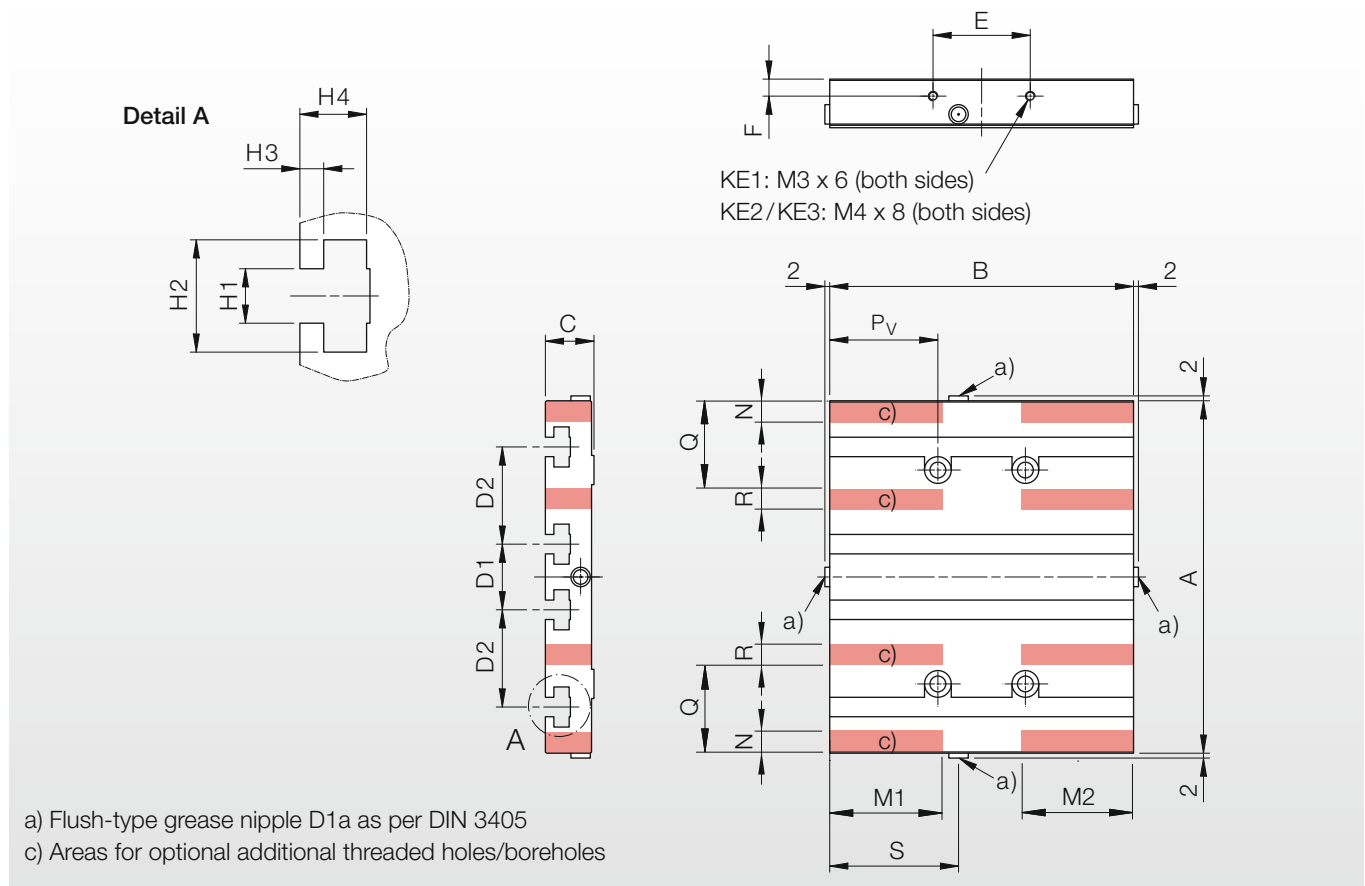
# COMPACT UNITS WITH BALL SCREW DRIVE



## Connecting plates for KE...2...R... with 1 carriage

Aluminium connecting plates for LINE-TECH compact units broaden the mounting options. They also permit position-independent greasing, as sufficient grease points are available on the connecting plates.

### Dimensions



Nominal size	Dimensions connecting plate [mm]													Weight [kg]	Item no.
	A	B	C	D1	D2	E	F	H1	H2	H3	H4	P <sub>v</sub>	S		
KE1.2...R...	90	60	16	20	20	30	8.5	6	12.0	3.5	7.7	16.5	37.0	0.183	G-10921
KE2.2...R...	110	60	16	20	20	40	7	6	12.0	3.5	7.7	15	37.5	0.213	G-10923
KE3.2...R...	145	125	20	27	40	40	7	8	16.5	3.5	9.8	44.5	53.0	0.727	G-10925

Nominal size	Dimensions of areas for optional additional threaded holes/boreholes [mm]				
	N	Q	R	M1	M2
KE1.2...R...	8.5	21.5	7	12	12
KE2.2...R...	—	31.5	7	17	17
KE3.2...R...	10	35	15	30	30



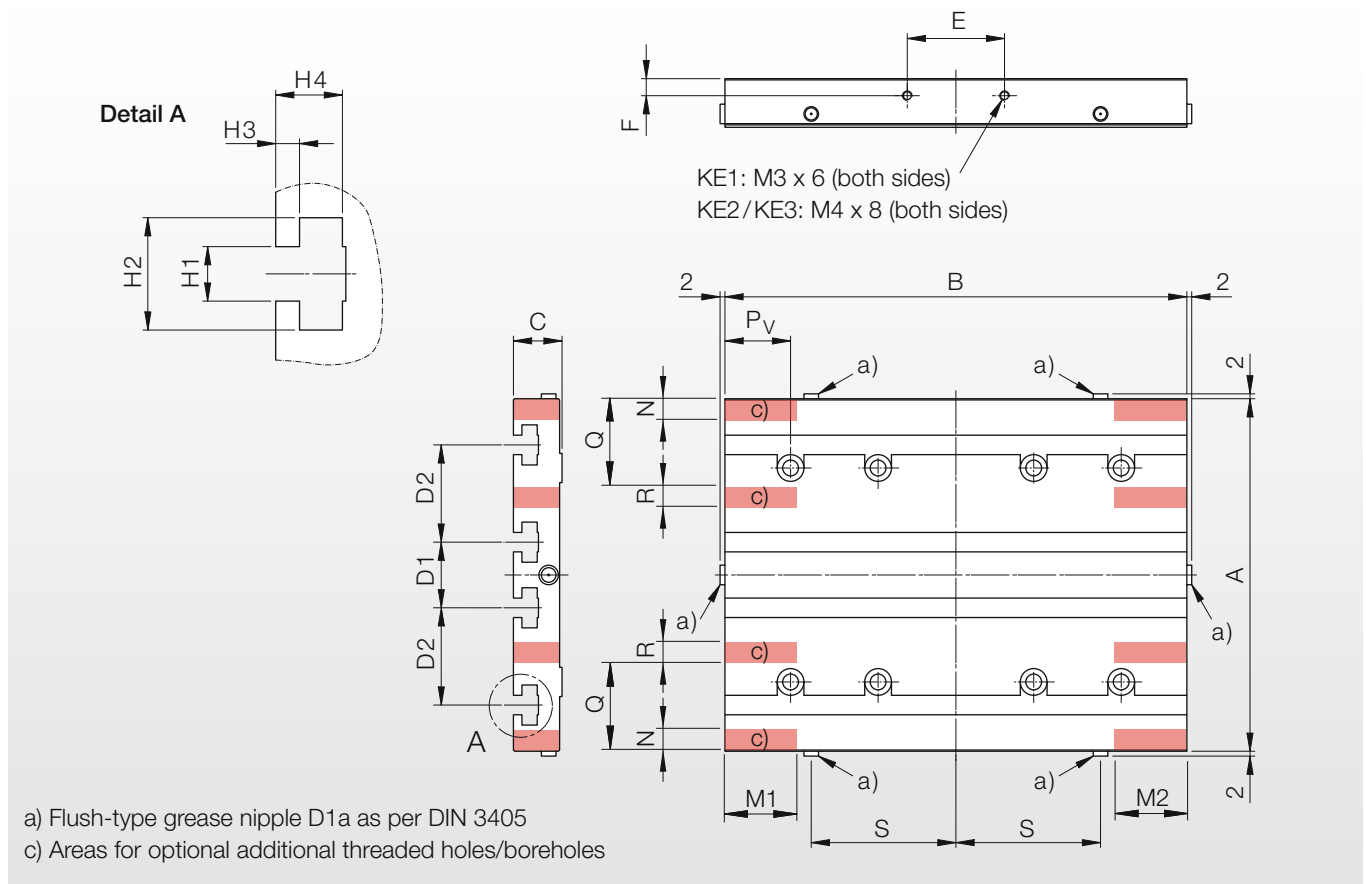


# COMPACT UNITS WITH BALL SCREW DRIVE



## Connecting plates for KE...4...R... with 2 carriages

### Dimensions



Nominal size	Dimensions connecting plate [mm]														Weight [kg]	Item no.
	A	B	C	D1	D2	E	F	H1	H2	H3	H4	P <sub>v</sub>	S			
KE1.4...R...	90	125	16	20	20	30	8.5	6	12.0	3.5	7.7	16.5	25.7	0.385		G-10922
KE2.4...R...	110	155	16	20	20	40	7	6	12.0	3.5	7.7	20	35.0	0.565		G-10924
KE3.4...R...	145	190	20	27	40	40	7	8	16.5	3.5	9.8	27	59.5	1.100		G-10926

Nominal size	Dimensions of areas for optional additional threaded holes/boreholes [mm]				
	N	Q	R	M1	M2
KE1.4...R...	8.5	21.5	7	30	30
KE2.4...R...	18	31.5	7	30	30
KE3.4...R...	10	35	15	30	30

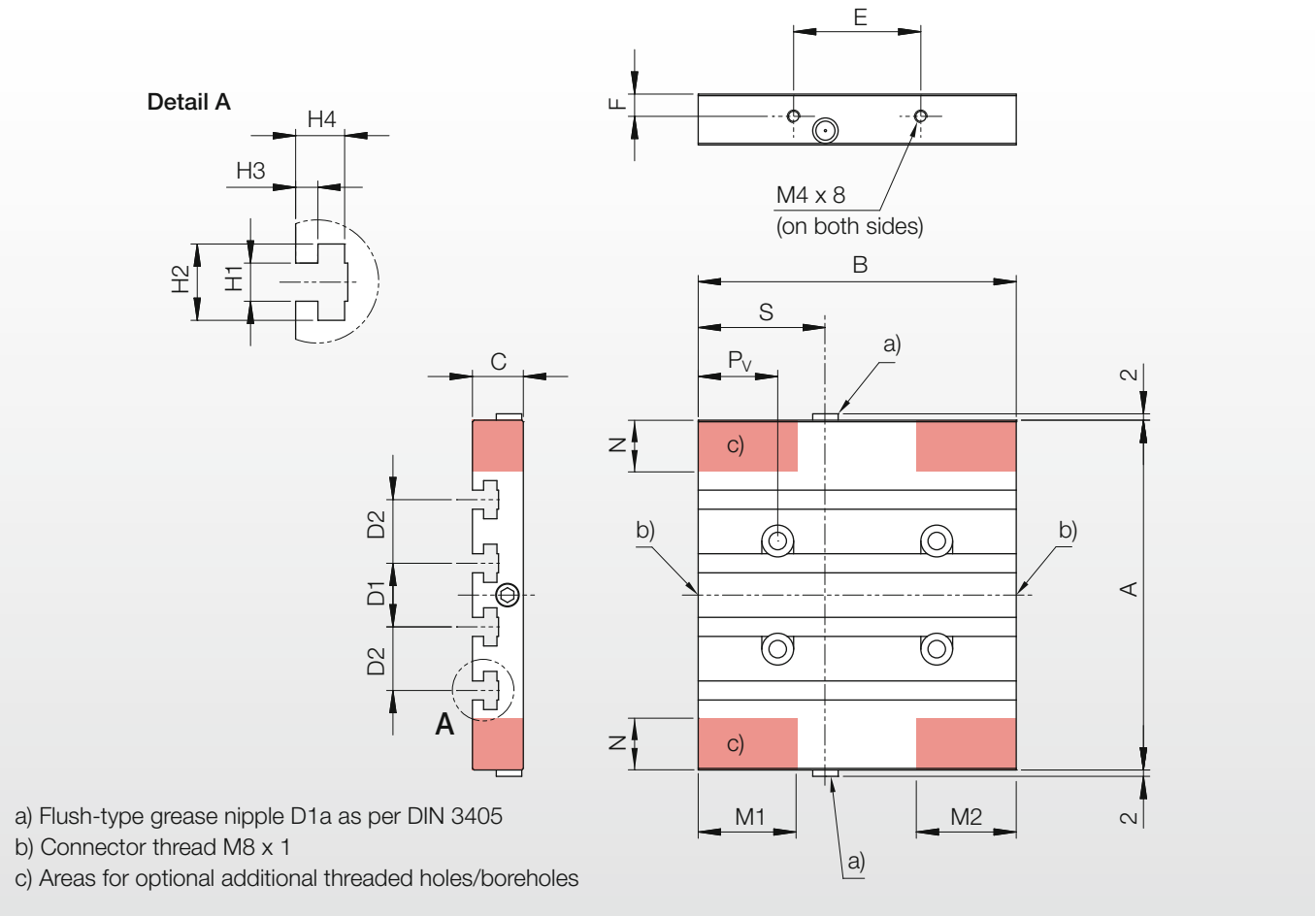




# COMPACT UNIT WITH TOOTHED BELT DRIVE

Connecting plate for KE2.2...Z... with short carriage (2 runner blocks)

## Dimensions



Nominal size	Dimensions connecting plate [mm]													Weight [kg]	Item no.
	A	B	C	D1	D2	E	F	H1	H2	H3	H4	P <sub>V</sub>	S		
KE2.2...Z...	110	100	16	20	20	40	7	6	12.0	3.5	7.7	25	40	0.402	G-10738

Nominal size	Dimensions of areas for optional additional threaded holes/boreholes [mm]		
	N	M1	M2
KE2.4...Z...	18	27	27





## COMPACT UNITS



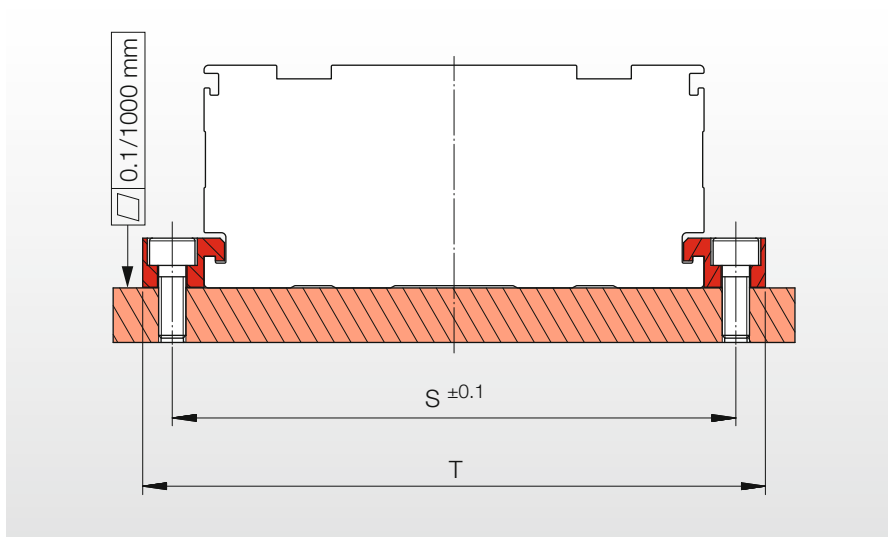
### Mounting accessories; clamping brackets

#### Mounting options

The compact units are attached using clamping brackets

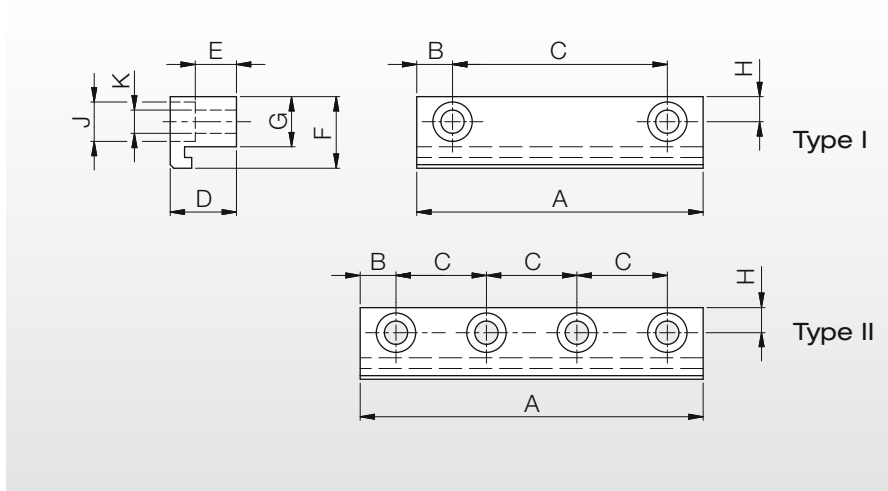
**Attention:** The compact units are to be attached to or supported by the base profile only, not the end plates.

Nominal size	Dimensions [mm]	
	S	T
KE1...	102	112
KE2...	126	140
KE3...	161	175



#### Clamps

Recommended number of clamps:  
4 per metre and side.



Nominal size	Dimensions [mm]											Weight [kg]	Item no.
	Type	A	B	C	D	E	F	G*	H	J	K		
KE1...	I	35	7.5	20								0.021	P-54434
	II	80	10	20	7.6	2.6	14.5	11	5	ø8	ø4.5	0.048	P-54435
KE2/3...	I	60		40								0.072	P-54179
	II	80	10	20	10.5	4.5	19.5	15	7	ø11	ø6.5	0.118	P-54181



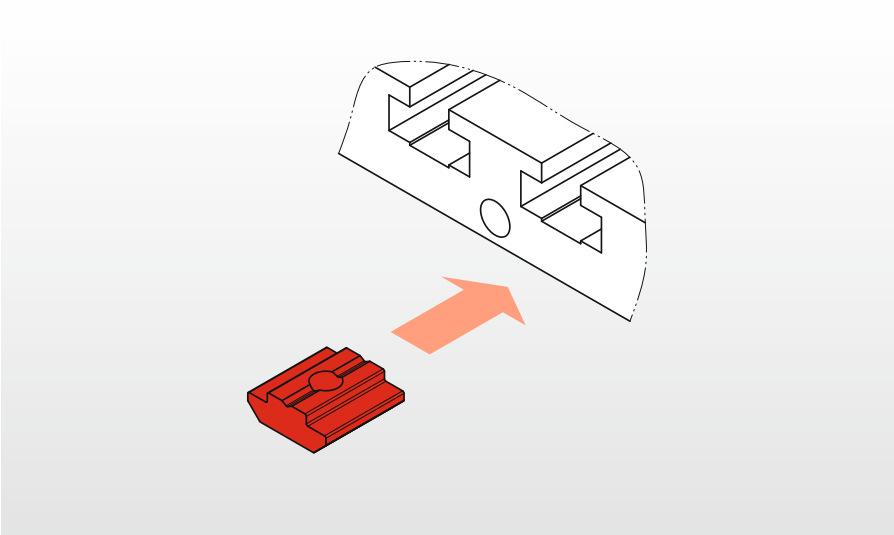


Attachment accessories; T-slot nuts for connector plates

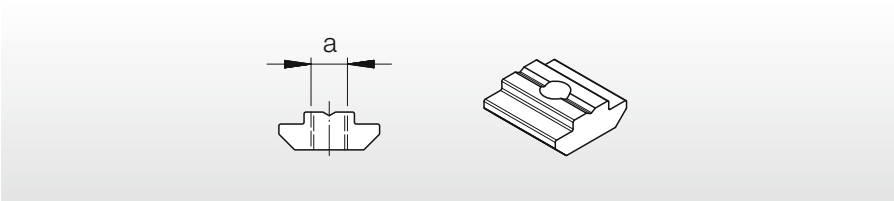
T-slot nuts

T-nuts with the corresponding T-slot width can be used to mount add-on parts on the connector plates (KE...V...).

Note: The T-nuts must be able to be inserted from the side.



T-nut types NS6 and NS8 can be used in line with the T-slot width (see connector plates, pages [40-43](#)).  
T-slot nuts are available from LINE TECH.  
Size, material and connection thread as per the following order system must be defined as the order number.  
The available types are listed opposite.



Dimensions [mm]		Material
T-slot width	a (thread)	
6 (KE1 / KE2)	M4 / M5 / M6	Steel
8 (KE3)	M4 / M5 / M6 / M8	Steel

Ordering system for T-slot nuts

Designation example:

Basic key				
NS	6	St	M5	KE
NS = T-slot nut		KE = for Compact units (Connecting plates)		
T-slot width » see connecting plates p. <a href="#">40-43</a>		Thread » size a as per table above		
6		M4 / M5 / M6		
8		Material		
		St = Steel		

## Cross table mountings

### Cross tables

LINE TECH compact units are also available as cross table units. Four mounting types are possible. The designation system opposite applies.

Cross table mounting layout AC and AD are fitted using clamps. The lower unit must always be the version with two carriages resp. long carriage and connector plate (KE...4...V...). For mounting layouts BC and BD, a special intermediate plate is fitted to the top units in addition. The individual compact units must be ordered separately.

### Accuracy

Standard accuracy for cross table mountings is 0.1 mm/300 mm stroke. Higher accuracy on request.

### Designation system

**KM . KE3 / KE2 . AC**

Cross table mounting

Abbreviation for lower unit

KE1 / KE2 / KE3 (Version KE...4...V... is required!)

Abbreviation for upper unit

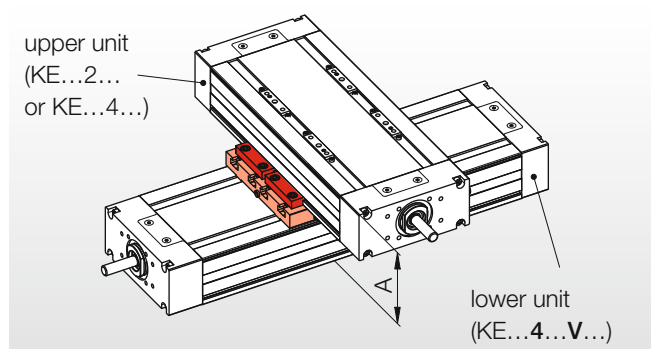
KE1 / KE2 / KE3

Mounting type

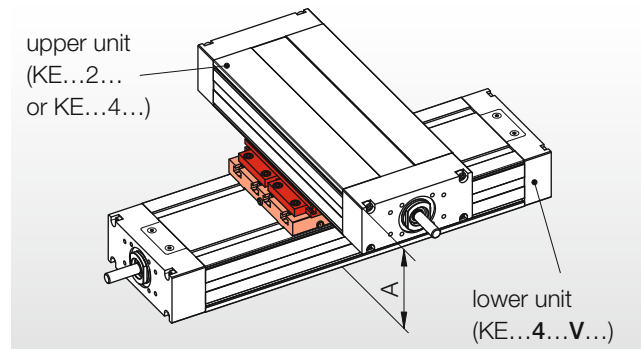
AC / AD / BC / BD

Dimension A [mm]		upper unit		KE2...		KE3...	
Mounting type		KE1... A..	B..	A..	B..	A..	B..
lower unit	KE1.4...V...	96	112	not possible			
	KE2.4...V...	106	122	116	132	not possible	
	KE3.4...V...	on request		135	151	150	169

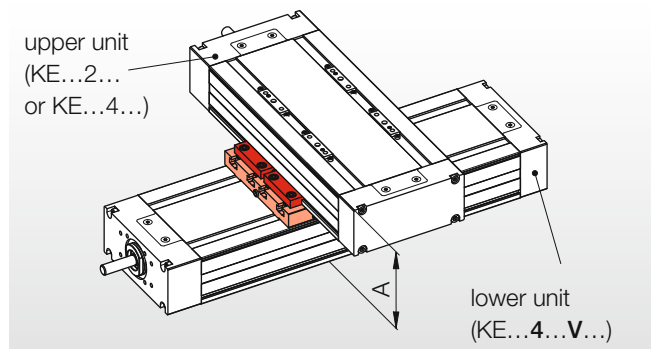
### Mounting layout AC



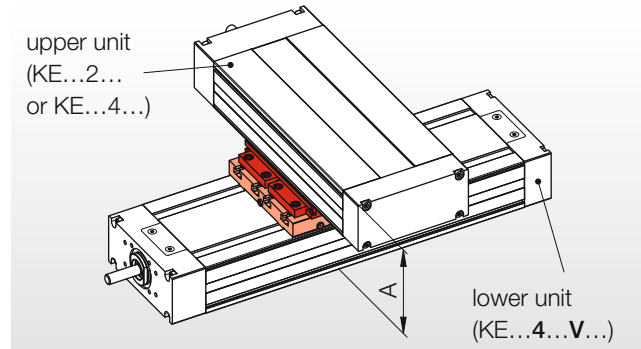
### Mounting layout BC



### Mounting layout AD



### Mounting layout BD

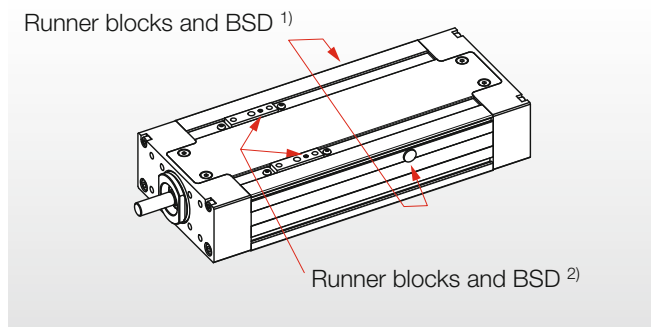


# COMPACT UNITS

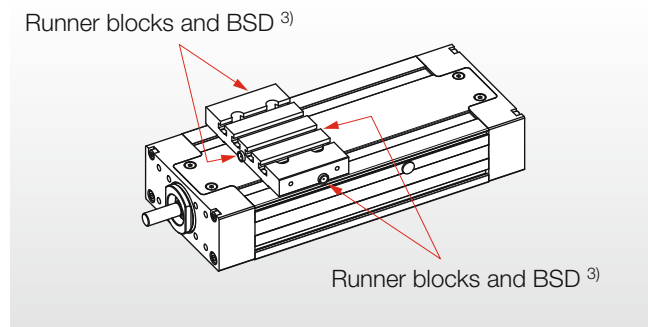


## Grease points

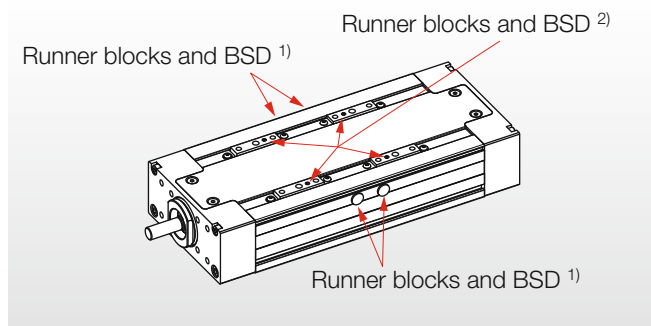
### KE...2...R...N...



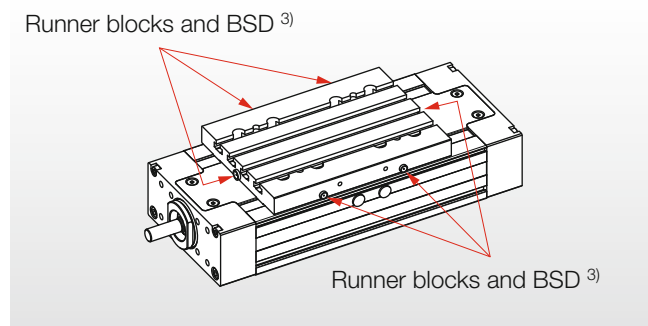
### KE...2...R...V...



### KE...4...R...N...



### KE...4...R...V...



## Grease points

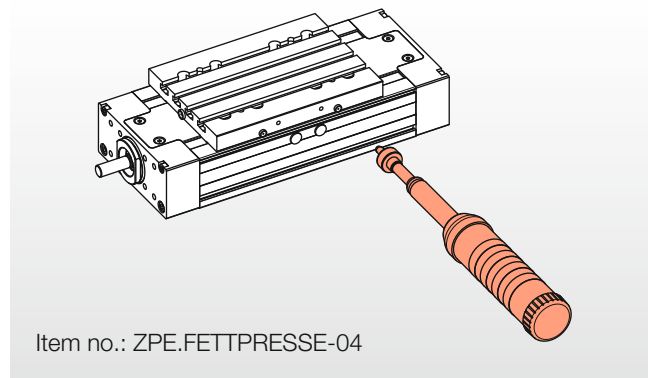
Different lubricating nipples are on the compact units:

- <sup>1)</sup> Lubrication nipples to DIN 3405; the cover caps must be removed for lubrication. The lubrication positions are as in the table below.
- <sup>2)</sup> The connection is as per the interface for customer add-on, page [49](#); the lubrication positions are not dependent on stroke.
- <sup>3)</sup> Lubrication nipples to DIN 3405; the lubrication positions are not dependent on stroke.

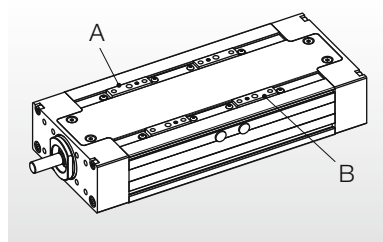
## Standard grease

LINE TECH recommends the following grease for lubrication:  
Microlube GBU Y 131

## Grease gun



## Carriage position for lubrication by the base profile



Stroke position [mm]	KE type					
	KE1.2...	KE1.4...	KE2.2...	KE2.4...	KE3.2...	KE3.4...
A: first carriage	Stroke / 2	Stroke / 2	Stroke / 2	Stroke / 2	Stroke / 2	Stroke / 2
B: second carriage	—	Stroke / 2	—	Stroke / 2	—	Stroke / 2 – 10

# COMPACT UNIT WITH TOOTHED BELT DRIVE



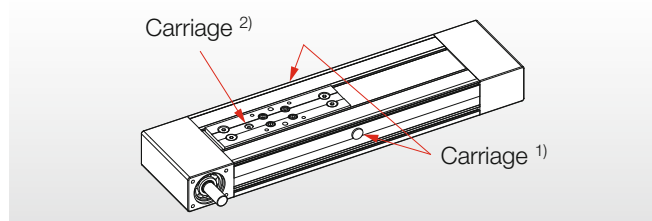
## Lubrication points

### Lubrication points

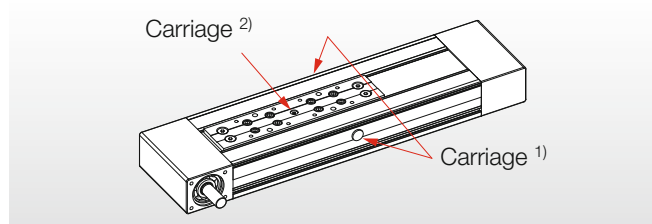
LINE TECH compact units KE...Z... are designed so that lubrication is required at one point only.  
The following lubrication options are available:

#### Lubrication through the base profile

KE...2...Z...N...

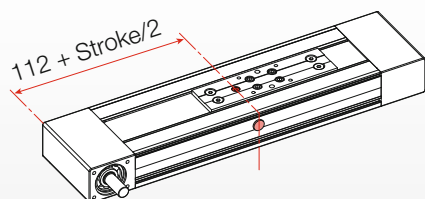


KE...4...Z...N...



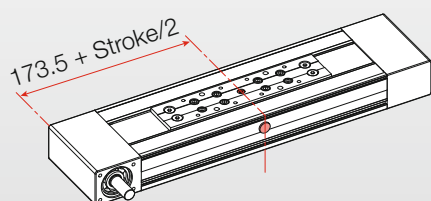
#### Carriage positions for lubrication through the base profile

KE...2...Z...N...



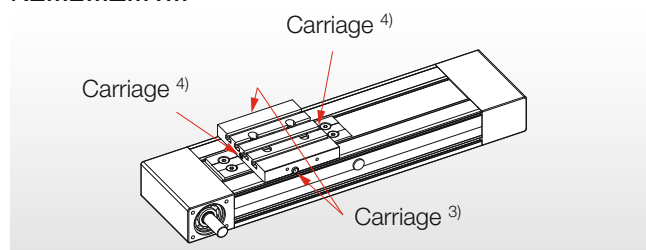
Align the lubrication point of the carriage with the lubrication nipple on the base profile.

KE...4...Z...N...

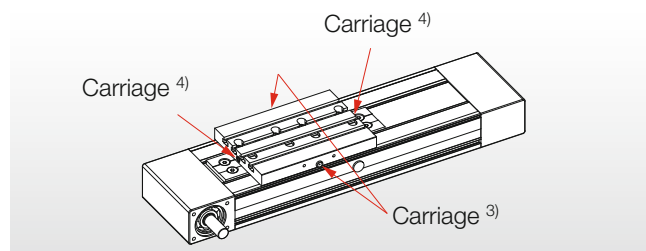


#### Lubrication through the connecting plate

KE...2...Z...V...



KE...4...Z...V...



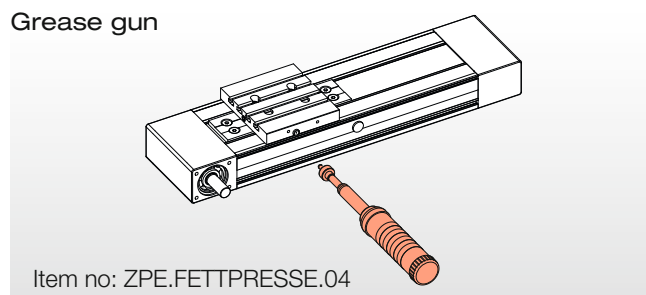
Various grease nipples are used on the LINE TECH compact units:

- 1) Grease nipple as per DIN 3405; the cover caps must be removed for lubrication. Lubrication positions according to the illustrations shown here.
- 2) Connection as per interface for customer add-ons, page [49](#); the lubrication positions are independent of the stroke.
- 3) Grease nipple as per DIN 3405; the lubrication positions are independent of the stroke.
- 4) Connection thread M8x1 (optional lubrication possibility).

#### Standard grease

LINE TECH recommends the following standard grease:  
– Microlube GBU Y 131

#### Grease gun



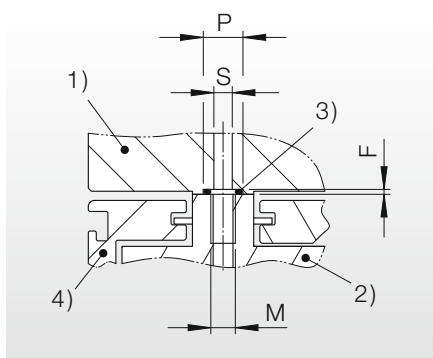


## Lubrication points for customer add-on

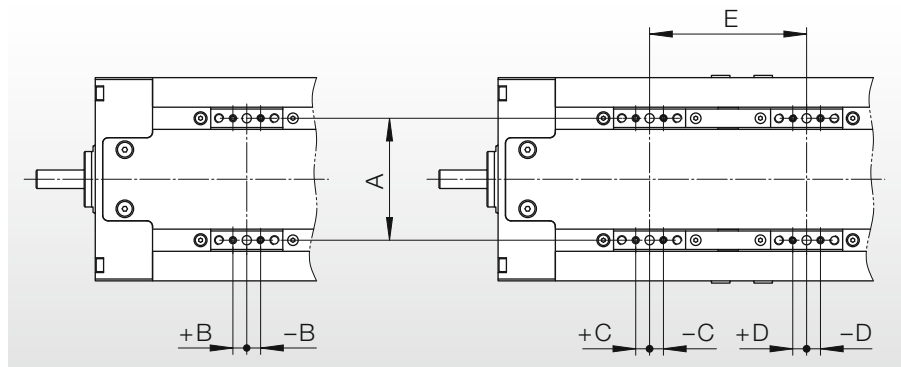
### Interfaces for lubrication connections for customer add-ons

The lubrication connections in the carriages are sealed with a grub screw as standard.  
To be able to use these lubrication points, the grub screws must be removed at each position.

#### KE...R...



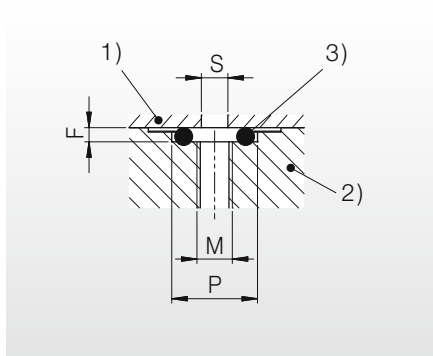
- 1) Add-on by customer
- 2) Carriage
- 3) O-Ring
- 4) Base profile



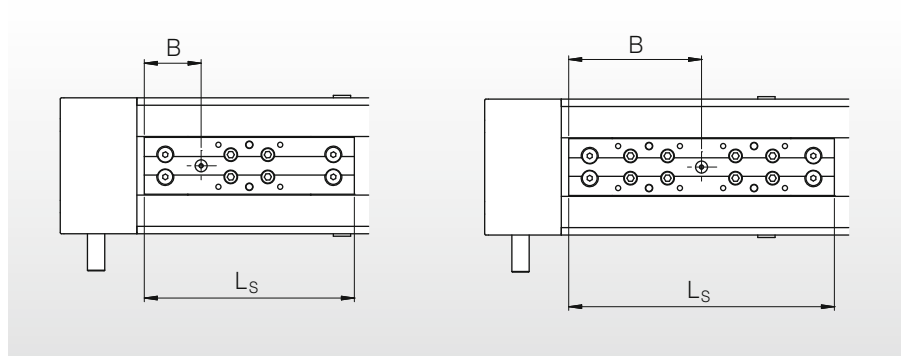
#### Dimensions [mm]

Size	A	B	C	D	E	F	M	P	S	O-ring
KE1...R...	54	-6.8	-6.8	6.8	65	0.8	M3	ø6.5	ø3	ø4x1
KE2...R...	66	-7.5	-7.5	7.5	85	0.8	M4	ø6.5	ø3	ø4x1
KE3...R...	88	11.5	11.5	-11.5	100	0.8	M5	ø6.5	ø3	ø4x1

#### KE...Z...

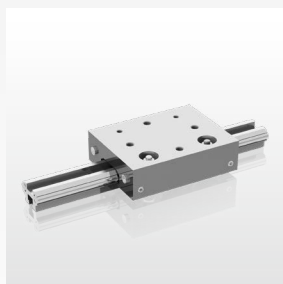
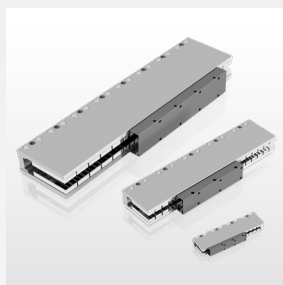
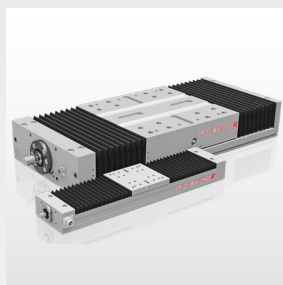


- 1) Add-on by customer
- 2) KE carriage
- 3) O-ring



#### Dimensions [mm]

Size	L <sub>s</sub>	B	F	M	P	S <sup>1)</sup>	O-ring <sup>1)</sup>
KE2.2...Z...	170	46	1.6	M4	ø9	ø3	ø5x2
KE2.4...Z...	215	107.5	1.6	M4	ø9	ø3	ø5x2



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