

≡ Linear module LM4...NZ...N XL with toothed belt drive

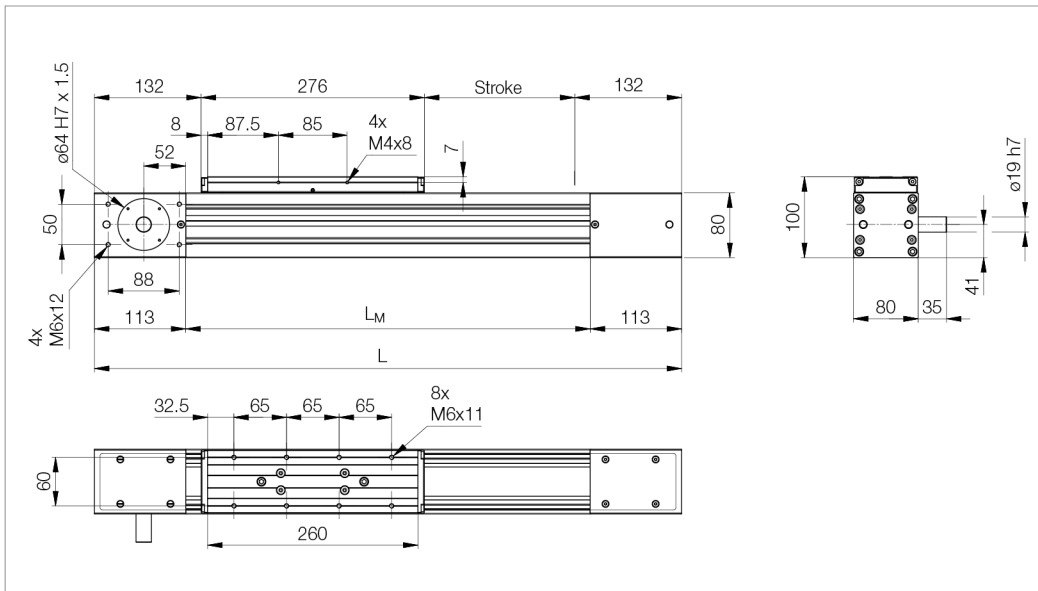
| LM | Toothed belt drive | | | | Axial load F [N] | Positioning accuracy [μ/mm] | Repeating accuracy .../1000 mm [mm] | Acceleration a_{max} [m/s ²] |
|------------|--------------------|---------------------------------|--------------------|---------------------------------|------------------------|--------------------------------|---|--|
| | Type/division | Pinion $d_3 \times l_p$ [mm] | Stroke/rev [mm] | Tension ³⁾ [mm/m] | | | | |
| LM4...Z... | HTD5M | 65.25 x 45 | 205 | 0.105 | ... ¹⁾ | 200/1000 ²⁾ | < 0.20 ²⁾ | 50.0 ¹⁾ |

$d_3 \times l_p$ = pinion diameter x pinion width

¹⁾ depending on speed and load

²⁾ backlash not factored in

³⁾ belt tension/metre [mm/m] per 100 N tensile force



| Nominal size | Dimensions | | | |
|--------------|--------------|---------------|---------------------|---------------------------------|
| Designation | L [mm] | L_M [mm] | Belt length [mm] | Weight [kg] |
| LM4...NZ...N | Stroke + 540 | L - 226 | 2 x Stroke + 900 | 8.40 kg + 0.93 kg/100 mm Stroke |

Variants/dimensions with protective strip (LM4...BZ...N) see catalogue

| LM | Movement speed | | Moments of inertia Z | | Stroke max. [mm] | Steel strip | Feed and friction force F_V [N] | Moved mass m_b [kg] |
|-------------|-----------------------------|-----------------------------|-----------------------------|-----------------------------|---------------------|-----------------|---|-----------------------------|
| | Guide v_{max} [m/s] | Drive v_{max} [m/s] | I_y [cm ⁴] | I_z [cm ⁴] | | | | |
| LM4...Z...N | 5.0 | ⁴⁾ | 131.2 | 197.8 | XL: 13880 | without with | 25.00 35.00 | 2.150 2.165 |

⁴⁾ for toothed belt drive, dependent on load and speed and permissible movement speed of the linear guide

| Linear modul Type | Maximum permissible load [kN] | | | | Maximum permissible torque [Nm] | | | | | |
|----------------------|-------------------------------|--------------|------------|------------|---------------------------------|----------|----------|---------|-------|-------|
| | static | | dynamic | | static | | | dynamic | | |
| | $C_{y0,1,2}$ | $C_{z0,1,2}$ | $C_{y1,2}$ | $C_{z1,2}$ | M_{x0} | M_{y0} | M_{z0} | M_x | M_y | M_z |
| LM4...Z...N | 59.9 | 59.9 | 34.2 | 34.2 | 646 | 2484 | 2484 | 400 | 2130 | 2130 |

The determination of dynamic load ratings and torques is based on a 50,000 m stroke. If comparative values must be calculated for a 100,000 m stroke, the values for M_x , M_y , M_z and C must be divided by the factor 1.26.

With a view to serviceable life, loads of less than 20% of the dynamic load ratings have generally proved to be expedient.